Image Edge Detection Based on Swarm Optimization Technique


Abstract: Detecting of the edges in the image is used for highlighting sharp values of intensities and also which is used to extracted the relevant data. In the traditional methods of detection the results will be in broken edges and thereby there is loss of contours. The Ant Colony Optimization (AnCO) is originated to have faith in the detection problems wherever the aim is to extract the sting data which is present in the input picture, which is necessary to grab the information. Most procedures regarding Ant Colony Optimization is the inventions of fine explore regeneration over across the secretion upgraded by the army of ants. AnCO is galvanized from the actions of hunting the food displayed by hymenopteran community to seek out estimate results to the robust problems. An Ant Colony Optimization algorithmic rule is that the combination of previous information relating to the structure of an answer with the data relating to the arrangement of antecedent to acquire smart results. This methods uses 5 steps as initialization, construction, update, decision and conceptualization method.

Here the proposed methodology is carried with test images such as lena and cameraman. This method in finding the edges from a binary image by investigation results shows the successful outcomes. This proposed work can be applied in biomedical image processing in finding out the contour of tumor tissues.

Key terms: (AnCO) Ant Colony Optimization; CANNY; SOBEL; PREWITT; Edge Detection; MSE; PSNR.

I. INTRODUCTION

These algorithms were galvanized by examining the actual ant army. Ants square measure the eusocial insecta that reside in colonies at intervals the first Nineteen Nineties, Ant Colony Optimization (AnCO) was bestowed by Marco Dorigo, A. Colorni and V. Maniezzo [1] as a unique informed – search based on bio-inspired technique to optimize the deteriorate issues of Integrative methods. The initial AnCO algorithmic program referred to as hymenopteron system that was planned by M. Dorigo.

Marco Dorigo and Luca Maria Gambardella revealed ACS in the year 1997 [3], and a range of these methods are evolved like Mini – Max [5] and ACS [4]. It utilize directly to gather the sting data from planned technique, in distinction to it AnCO is a *post-proc* to boost sting data which is already taken from edge standard detection methods.

Here we try to review different methods to get higher solutions. AnCO is algorithmic program which is galvanized by the life of ants in natural behaviour, ants sediment secretion while following the path for food on the earth [3], [4]. During the algorithmic program, the suitable method is searched by ants so as to seek out the answer house. Dorigo et al. planned the primary AnCO algorithmic program, ant system [2], [4]. It is present formally that AnCO to tackle the drawbacks of detecting the edges of image. The main idea is to collect the sting data bestowed within the picture, since it's important to know the content in the image.

II. LITERATURE SURVEY

Numerous researchers have worked on detecting the image edges which enlisted below.

Maini Raman & Dr. Aggarwal Himanshu planned the contrast of different techniques in detecting edges in traditional and mathematical methods such as Gradient and Laplacian edge detection. Prewitt operators have a serious noise problem. Mask size and coefficients square measure are mounted, it can't be custom to a given image. Moreover, Associate in nursing algorithmic program in detecting the edges adaptively is critical to produce a strong resolution. i.e It varies to the different levels of noise of those pictures which assist discriminate the valid contents of the image from the artifacts which is generated by noise.

Gianni Di Caro, Luca M. Gambardella, Marco Dorigo planned Emmet algorithms for separate optimization that introduces the AnCO meta-informed search and therefore the biological location of ants existent and its affected counter elements have different variety of applications to combinatorial optimization and routing in communications networks square measure is described precisely.

Shweta Agarwal performed Edge detection in Blurred pictures exploitation AnCO method. Detecting the edges in blur pictures exploiting and prioritizing totally dissimilar values of colour internals of importance and strength. The algorithmic program doesn't think about deblurring of image and therefore terminate the probabilities in loss of information and a image blur can manufacture various edges in a neighborhood of interest. Some of the edges are unrecognized and some of the edges are helpful.
III. IMAGE EDGE DETECTION

Detecting the edges refers to the obtaining the sides in an exceedingly image. It is a train of actions which aims to the spot dots in a picture wherever the intensity changes will occur due to the gaps or precise edges. This sequence of action is essential to know the information of a picture. Associate in nursing these edge points which are extracted from a picture which gives an understanding the vital parameters carried out in the analysis and computer vision. For extracting the features and appearance it plays as a pre-processing unit. In early stages of computer vision applications this technique is applied. The main use of operative work in the intensity of image is to collect the essential occurrence and changes within the substantial properties of the planet. Intensity changes sometimes assumes two types of occurrence concerning to the acquiring the image forming methods such as Geometric and Non-geometric occurrences.

A geometric occurrence incorporates irregularities in surface, texture and colour. Non-geometric occurrences incorporates dynamical incandescence, and standard operators to detecting the edge like SOBEL, PREWITT, ROBERT’s, LOG operator and different operators for detection techniques which is used to measure square computation, every action of set is managed for each element. In traditional methods, the estimation time rises quickly in the scale of image. Nevertheless, almost all the detection methods use an enormous forage house for detecting the edges. Consequently, while optimizing sting detection of image task is memory storage and time of execution. Associate in Nursing Ant Colony Optimization has the future of getting control over the restrictions of standard ways.

Various methods of ant colony optimization approaches to the sting detecting edges drawback are planned. ACS is the initial AnCO algorithmic program. In view of its development, variety of supplements have emerged, the successful ones is Ant Colony System.

IV. TRADITIONAL OPERATORS

The aim of detecting the edges is to relevantly reducing the data in given picture, meanwhile restoring the relating properties for processing the image. Edges which are boundaries between different textures in the image or it can be disruptions in intensity from one picture element to another. For an image the edges are always dominant attributes which indicate the higher frequency. Detecting of edges will be helpful for segmenting the image, compression of data, and for matching such as reconstruction of the image and so on. We have studied different edge detection algorithms for different classes of images and have done a comparative analysis of all the results of traditional methods of detecting the edges such as SOBEL, PREWITT and CANNY operator.

A. CANNY Detection:

This method of detecting an edge uses an algorithm which is a multi-stage to detect a broader range of edges in images. This technique is used to retrieve related data from distinct perception objects and process the information which is adequately decreased.

The Canny detection method was outlined to be an excellent in detecting the edge. Source image must be a gray scale and produces response which shows the intensity discontinuities movement’s positions. The multi-stage algorithm can suppress the noise and detect the edges.

- Level evenly a Gaussian filters with image to remove noise levels and the textures which are not required.
  \[ g(m, n) = G_r(m, n) * f(m, n) \]
  Where \[ G_r = \frac{1}{\sqrt{2\pi \sigma^2}} \exp \left( -\frac{m^2 + n^2}{2\sigma^2} \right) \]

- Compute \( g(m,n) \) by different descent operators likes ROBERTS, SOBEL, PREWITT
  \[ M(m, n) = \sqrt{g_{m,m}^2(m, n) + g_{m,n}^2(m, n)} \]
  And
  \[ \theta(m, n) = \tan^{-1} \left[ \frac{g_{m,n}(m, n)}{g_{m,m}(m, n)} \right] \]

- To calculate the threshold \( M \)
  \[ M_r (m, n) = \begin{cases} M(m, n) & \text{if } M(m, n) > T \\ 0 & \text{otherwise} \end{cases} \]

Where T is approximated and all elements across the edges are unchanged meanwhile suppressing the noise.

B. PREWITT Detection:

The Prewitt Detection technique is named later JUDY PREWITT. Prewitt masks are based on the central difference of the pixel. Assume the picture elements in array about the centre pixel \([i,j]\) which is shown below:

\[
\begin{bmatrix}
g_0 & a_1 & a_2 \\ a_7 & [i,j] & a_3 \\ a_6 & a_5 & a_4
\end{bmatrix}
\]

The derivatives of this operator are calculated partially as:

\[ G_x = (a_2 + a_3 + a_4) - (a_0 + a_7 + a_6) \]

And

\[ G_y = (a_6 + a_5 + a_4) - (a_0 + a_1 + a_2) \]

This technique is less vulnerable to noise.
C. SOBEL Detection:

This technique is also called as SOBEL-FELDMAN technique or SOBEL filter. This technique has applications in the image processing and computer vision, detection methods creates emphasizing edges in image.

- This operator depends on the central dissimilarities which results weights to be larger with respect to the centered pel while doing the average.
- The SOBEL mask is better when compared with the CANNY mask in suppressing the noise.

\[ G_x = (a_2 + 2a_3 + a_4)(a_6 + 2a_7 + a_8) \]
\[ G_y = (a_6 + 2a_5 + a_4)(a_8 + 2a_2 + a_3) \]

V. PERFORMANCE OF ANCO ALGORITHMIC PROGRAM

ANTS which are artificial recapitulate construction loop while biasing with the bogus secretion test and therefore the heuristic data. The technique of AnCO is that the locating of excellent tourists is feed backed by updating the secretion of the ants. As the journey of ant’s is shorter, the secretion deposited by the ants is additionally placed on the path, thus it forces to pick out identical curves by repetition of the algorithmic program. The incidence of curves with high secretion values the square measure additionally strengthens the mechanism of secretion evaporation which avoids the infinite quantity of secretion and reduces the secretion content from the arcs that seldom receive extra secretion.

AnCO is galvanizing by forage behavior of food by the ant army that it hymenopterous insects as people are unsophisticated living beings could be a nature inspired optimization algorithmic program. Purpose of reading by few biologists’, the sensory optical organs of the $64000$ world ants square measure rudimentary naturally and they’re utterly blind. They communicate employing a chemical substance referred to as secretion. In journey of Associate in nursing in ants which accumulates continuing quantity secretion where different ants will follow. Initially all the ant move in an exceedingly random way, however once Associate in Nursing ant encounters a secretion path, it should settle a problem whether to follow or not. When the path has come, the secretion of ant reinforces this path, and therefore the growth in secretion will increase the chance of future ant choosing the trail. As the result, the additional ants travel on the same path engaging the trail becomes for consecutive ants. What is more, Associate in Nursing ant employing a short route to a food supply can come back to the nest faster and as result it marks the path doubly, before the different ants arrives. It straightly effects the choice of chance for future ant outbound in the nest.

Meantime, as additional ants square measure have the ability to finish the shortest path. On shortest path secretion assembles quicker and therefore the longest paths square measure lesser and at last abandoned. On smaller paths secretion densities will be more as a result of secretion is ordered down quicker. While in search of food the ants releases the stream of pheromones where the concentration of the pheromones is too high. These streams square measure creates in search of food. The amount of secretion of pheromone is high in density at extremely visited paths owing to the house cosmopolitan by the ants to achieve the source for the food and returns nest. The observations lead to the smaller path to follow by the ants. This is usual expertise which inspires the occurrence of the informed-heuristic AnCO.

VI. ANCO METHOD IN DETECTION OF EDGES

In the planned technique, variety of ants move in a two dimensional picture, moving from one element to a different to build a secretion matrices, which confirms stig data for a every element location within the image to extract the sides. The variation in the intensities values gives the motion of the ants. Edge detection method has the subsequent steps: initial is that the data formatting method. After building the secretion matrix by the AnCO once it takes off the N no. of iterations additionally. This method consists of construction method and update method. The last is conceptual method by which edges is set.

A. Initialization Method

For a image I of M ×N size consider input that answers house for bogus ants. The K numbers of ants square measure which is affected across the full picture such that each element of the image is consider as a node. For every element a constant is assigned and each element of the secretion matrix.

B. Construction Method

In ordinal step of construction, one hymenopteran being hand-picked from L total hymenopterans and this ant can give way for K steps. This hymenopteran can move from the (1m) to (i, j) i.e neighbour element , the transition chance given by

\[ P((i,j)) = \frac{(r_{ij}^{N-1})^a (n_{ij})^b}{\sum_{j \in \Omega_i} (r_{ij}^{N-1})^a (n_{ij})^b} \]

Here the position at (i,j) is the neighbourhood of position at (1,m) which represents the phenrome value, information at position (i,j) is represented by n_{ij}. The terms a and b represents the heuristic, phenrome matrices respectively.

This Procedure consists of 2 important topics and these are listed as follows:

In local statistic, location of pixel at (i, j) is evaluated as

\[ n_{ij} = \frac{1}{z_{(i,j)}} \]
Where $z$ is a factor of normalization, $v_i, (I(i,j))$ represents the set of variables of a pixels which are locally grouped and is called as clique. More precisely, for the pixel element $I(i,j)$ below consideration is assumed, the function $Vc(I(i,j))$ is $Vc(I(i,j)) = f(|li-2,j-1 - li+2,j+1| + |li-2,j+1 - li+2,j-1| + |li-1,j-2 - li+1,j+2| + |li-1,j-1 - li+1,j+1| + |li-1,j-1 - li+1,j+1| + |li-1,j+1 - li+1,j-1| + |li-1,j+2 - li-1,j-2| + |li,j-1 - li,j+1|)$.

The function $f(.)$ in above expression is calculated by the mathematically expression as follows:

$$f(x) = \lambda x, \quad for \ x \geq 0,$$

$$f(x) = \lambda x^2, \quad for \ x \geq 0,$$

$$f(x) = \begin{cases} \sin \left( \frac{\pi x}{\lambda} \right), & 0 \leq x \leq \lambda; \\ \frac{\sin \left( \frac{\pi x}{\lambda} \right)}{\lambda}, & \lambda < x \leq \lambda; \\ 0, & \text{else.} \end{cases}$$

Here the variable $\lambda$ in each above expression adjusts the functions shapes respectively.

**C. Updation Process**

In this approach to update the pheromone matrix it executes two updates operations.

- The first updating process is executed after the each ant moves within the each step of construction. Each element of the Pheromone matrix will be updating from the below expression

$$t_{i,j}^{(n-1)} = \begin{cases} (1-\rho) \times t_{i,j}^{(n-1)} + \rho \times \delta_{i,j}^{(0)}, & \text{if } (i,j) \text{ belongs to the best tour}, \\ t_{i,j}^{(n-1)}, & \text{otherwise.} \end{cases}$$

- The second updating process is carried out after the action of all the ants within the each step of construction

$$t(n) = (1-\varphi) \times t(n-1) + \varphi \times t(0)$$

**D. Decision Process**

At pixel location the binary decision is made to calculate if it is edge or not. Applying the value of $T^{(n)}$ on the pheromone matrix $T$ ($N$). In this paper, $T$ is computed based on the below developed method

Step 1:

$$T^{(n)} = \frac{\sum t = 1: M1 \times \sum j = 1: M2 \times t^{(n)}_{i,j}}{M1 \times M2}$$

Step 2:

$$m_i = \frac{\sum t = 1: M1 \times \sum j = 1: M2 \times \delta_{i,j}^{(1)} \times (t^{(n)})_{i,j}}{\sum t = 1: M1 \times \sum j = 1: M2 \times \delta_{i,j}^{(1)}}$$

$$m_i = \frac{\sum t = 1: M1 \times \sum j = 1: M2 \times \delta_{i,j}^{(1)} \times (t^{(n)})_{i,j}}{\sum t = 1: M1 \times \sum j = 1: M2 \times \delta_{i,j}^{(1)}}$$

$$h_i^{(1)}(x) = \begin{cases} x, & if \ x \geq T^{(1)} \\ 0, & otherwise \end{cases}$$

$$h_i^{(2)}(x) = \begin{cases} 1, & if \ x \geq T^{(2)} \\ 0, & otherwise \end{cases}$$

**E. Conceptualize Method**

In this method, completely dissimilar values of the $S_i (\psi)$ unit area parameter is applied on top of algorithmic rule. Smaller the worth of the letter of the alphabet parameter a lot of edges the algorithmic rule detects within the picture. We tend to persist decrease in the worth of the values i.e letter or alphabet, the given image output becomes clear but must not be zero.

<table>
<thead>
<tr>
<th>Limiting Factors</th>
<th>Limiting Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$1$ (entire ants)</td>
<td>$\sqrt{N1\times N2}$</td>
</tr>
<tr>
<td>$\rho$ (vaporization rate)</td>
<td>$0.0009$</td>
</tr>
<tr>
<td>$\lambda$ (constant)</td>
<td>$1$</td>
</tr>
<tr>
<td>$\tau_{init}$ (Each position of pheromone matrix i.e initial position)</td>
<td>$0.0001$</td>
</tr>
<tr>
<td>$\alpha$ (Pheromone matrix factor)</td>
<td>$2$</td>
</tr>
<tr>
<td>$\beta$ (Heuristic matrix factor)</td>
<td>$0.009$</td>
</tr>
<tr>
<td>$K$ (Construction Step which includes number of ants move)</td>
<td>$300$</td>
</tr>
<tr>
<td>$\psi$ (Decaying coefficient of Chemical Substance)</td>
<td>$0.0009$</td>
</tr>
<tr>
<td>$N$ (Number of construction steps)</td>
<td>$50$</td>
</tr>
<tr>
<td>$\varepsilon$ (In the decision process tolerance value is user-defined)</td>
<td>$0.1$</td>
</tr>
<tr>
<td>$\Omega$ (tolerable Ant’s tolerable range)</td>
<td>$8$ neighbour connectivity</td>
</tr>
</tbody>
</table>

The solution relies on the final secretion matrix values. The previous works applies a threshold value technique, specifically referred to threshold method or by the tactic to cut back the ensuing gray scale picture to a binary picture with solely 2 potential values for every constituent element who is able to classify every constituent element as either a grip or not an edge. Though, it involves analyzing the activity dispensed by the pismire entirely in detecting the edges, as a result the numerous levels of intensities is simply pretty good as a grey scale declaration. Hence, in connect of levels in the ant’s edge detection; the result would be direct results of final secretion matrix values. Here a binary call is created at every constituent location to work out whether it is edge or not. To eradicate this it creates a threshold $\tau$ by applying on the ultimate secretion matrix. Here the edge value $\tau$ is computed which is chosen adaptively.
VII. PROPOSED APPROACH

- Randomly dispatch ants on image
- Initialize the pheromone matrix
- Calculate the heuristic matrix

Construction Method: Select the 1\textsuperscript{st} ant then move N steps, from probability matrix

Updation Method: updating the pheromone

VIII. EXPERIMENTAL RESULTS

Investigation are done to analyze the this technique performance on these test images i.e Cameraman and Lena which are given in figure (a), figure (b) respectively. In addition, several factors of the proposed approach are listed below.

- \( L = \sqrt{(N1 \times N2)} \): Entire ants, the term \( x \) denotes the largest value, i.e. equals or smaller to \( x \).
- Unit = .0001: initialization of Pheromone Matrix
- \( \alpha = 1 \): Factor of Pheromone.
- \( \beta = 0.1 \): Factor of Heuristic.
- \( \Omega = 8 \)-neighbourhood connectivity: the acceptable range of movement.
- \( \lambda = 1 \): Rectifying value.
- \( \rho = .1 \): Vaporization rate.
- \( N = 50 \): Entire ant’s moving in each construction-step.
- \( \psi = 0.05 \): Decaying value of chemical substances.
- \( \varepsilon = 0.1 \): In the proposed method decision process tolerance value is user-defined.
- \( L = 2 \): total number of construction-steps.

The calculation of above factors of proposed technique performance is critical which may report later. Empirical solutions differentiate the heuristic methods with traditional methods such as SOBEL, CANNY, PREWITT operators.

In addition, to the proposed method evaluating the matrix of heuristic is much crucial and to eradicate this various methods are stated and added in the proposed method. The result are enlisted below, figures (a) and figure (b) represent the test images of a Cameraman, Lena respectively. From below Figures (3) & (4), the proposed approach always outperforms when compared with traditional method results which is shown below in figures 1 & 2 in terms of perceptible feature information of the extracted edge.

The proposed method of AnCO detection of edge approach has carried out in the MAT LAB.

Figure (1) Lena original image, traditional technique outputs

Figure (2) Cameraman Original Image, Traditional Technique Outputs

Figure (3) Cameraman_ACO

Figure (4) Lena_ACO

The result are enlisted below, figures (a) and figure (b) represent
IX. EXPERIMENTAL RESULT VALUES IN TABULAR FORM

Experimental values for Cameraman:

<table>
<thead>
<tr>
<th>Parameters</th>
<th>CANNY</th>
<th>SOBEL</th>
<th>PREWITT</th>
<th>ACO</th>
</tr>
</thead>
<tbody>
<tr>
<td>ENTROPY</td>
<td>1.9055</td>
<td>1.5342</td>
<td>2.8325</td>
<td>0.330</td>
</tr>
<tr>
<td>TIME OF EXECUTION (SEC)</td>
<td>0.002</td>
<td>0.006</td>
<td>0.005</td>
<td>0.007</td>
</tr>
<tr>
<td>MSE</td>
<td>94.5944</td>
<td>89.789</td>
<td>71.5286</td>
<td>60.904</td>
</tr>
</tbody>
</table>

Experimental values for Lena image:

<table>
<thead>
<tr>
<th>Parameters</th>
<th>CANNY</th>
<th>SOBEL</th>
<th>PREWITT</th>
<th>ACO</th>
</tr>
</thead>
<tbody>
<tr>
<td>ENTROPY</td>
<td>6.094</td>
<td>1.194</td>
<td>2.297</td>
<td>0.407</td>
</tr>
<tr>
<td>TIME OF EXECUTION (SEC)</td>
<td>0.002</td>
<td>0.006</td>
<td>0.006</td>
<td>0.007</td>
</tr>
<tr>
<td>MSE</td>
<td>94.792</td>
<td>89.789</td>
<td>71.527</td>
<td>69.715</td>
</tr>
</tbody>
</table>

X. CONCLUSION

Associate degree AnCO-based detection of edges in an image takes benefits of enhancements in Ant Colony System which is obtained successfully and tested. Investigational solutions display likelihood of the method in distinguishing edges in a picture.

The MSE of this method is low compared to SOBEL and this algorithmic rule results in a pair of to five increase in Peak signal to noise magnitude relation of projected algorithmic rule compared to it of SOBEL and clever algorithmic rule.

The result of the proposed method the entropy is much lesser than the traditional method which relates to state of intensities. The mean square error is much lesser when compared with the traditional technique.

With acceptable values, it was able to verify the sides successfully within the check pictures. It is ought to be notice that approximated values will be from the image, and thus, might change according to the task.

The area unit of ants are assigned unique secretion level, that makes few ants to be sensitive to secretion when compare to the others. The next level, nonidentical pismire army with new communication methods was used. The projected ACS methodology for detecting the edge can be updated by creating the use of these techniques.

REFERENCES


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