

C-Ideal Via C-Topological Space



Dheargham Ali Abdulsada, Luay A.A. Al-Swidi

Abstract: The purpose of this paper is to present a new family called C-ideal by using the center set and study the most important properties of this family, in addition, to define new points via C-ideal called, C-turning and C-bench points with respect to C-topological space.

Keywords : Center set, C-topology, C-ideal, C-turning point and C-bench point

I. INTRODUCTION

The concept of proximity space is one of the important concepts introduced by mathematician Efremov in 1951 [1], which was considered an axiom of geometry and suitable instruments for the investigation of topology. More comprehensive work on the proximity space was carried out by Naimpally and Warrack [2]. Many authors have worked on the concept of proximity space.

In [4], Focus on different approaches to distinctive patterns in non-empty sets that have to do with proximity theory and the discovery of new patterns in proximity, In [5], they discussed the spatial and descriptive relationships of proximity theory. In [6], an explicit description of the properties of separation axioms T_0 and T_1 was derived at the p point in the surface category of proximity space. In [7], an explicit description has been given of the separation properties for $T_0, T_1, Pre - T_2$ (*pre - Hausdorff*) and T_2 (*Hausdorff*) is given in the topological category of proximity spaces. In [8], Presented planar shape signatures derived from homology nerves, which are intersecting 1-cycles in a collection of homology groups endowed with a proximal relator (set of nearness relations) that includes a descriptive proximity. In [9], It's been deduced with showing that every connected asymptotic resemblance space induces a coarse proximity if and only if the connected asymptotic resemblance space is asymptotically normal. In the extreme

importance shown above, the authors D. A. Abdulsada and L. A.A. Al-Swidi in 2019 [10] used proximity space to define a new set called center set. In [11], used center set to define a new topology called C-topology. In this paper, we will explain the concept of C-ideal by relying on the center set and explain the most important theories with studying C-turning, point.

II. PRELIMINARIES

In this section we will describe the basic concepts that we will use in this paper.

Definition 2.1.[2].

Let X be a nonempty set and $\delta \subseteq P(X) \times P(X)$ a binary relation, then (X, δ) is proximity space iff for each $A', A'', A''' \subseteq X$,

1. $A' \delta A''$ iff $A'' \delta A'$;
2. $A' \delta (A'' \cup A''')$ iff $A' \delta A''$ or $A' \delta A'''$;
3. $X \bar{\delta} \emptyset$;
4. $\{x\} \delta \{x\}$ for each $x \in X$;
5. $A' \bar{\delta} A''$ implies there is an $E \subseteq X$ such that $A' \bar{\delta} E$ and $(X - E) \bar{\delta} A''$;

where $A' \bar{\delta} A''$ means it is not true that $A' \delta A''$.

Proposition 2.2.[3].

Let (X, δ) be a proximity space. Then
If $A' \delta A''$ and $A'' \subseteq A'''$, then $A' \delta A'''$;

1. If $A' \bar{\delta} A''$ and $A''' \subseteq A''$, then $A' \bar{\delta} A'''$;
2. If there exists a point $x \in X$ such that $A' \delta \{x\}$ and $\{x\} \delta A''$, then $A' \delta A''$;
3. If $A' \cap A'' \neq \emptyset$, then $A' \delta A''$;
4. $A' \bar{\delta} \emptyset$ for every $A' \subseteq X$;
5. If $A' \delta A''$, then $A' \neq \emptyset$; and $A'' \neq \emptyset$.

Definition 2.3.[10].

Let (X, δ) be a proximity space and $A \subseteq X$. A center set is $C_A = \{ \langle A, A' \rangle : A \delta A' \}$.

Definition 2.4.[10].

For two center sets C_A and C_B over a proximity space (X, δ) . Then

1. $C_X = \{ \langle X, A \rangle : \emptyset \neq A \subseteq X \}$ is called universe center set.
2. $C_\emptyset = \emptyset$ is called Null center set.
3. $C_A \preceq_c C_B$ iff $A \subseteq B$, and $\langle A, C \rangle \in C_A \Rightarrow \langle B, C \rangle \in C_B$.
4. $C_A = C_B$ iff $C_A \preceq_c C_B$ and $C_B \preceq_c C_A$.
5. $C_A \subseteq_c C_B$ iff $\langle A, C \rangle \in C_A \Rightarrow \langle B, C \rangle \in C_B$.

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6. $\mathcal{C}_A =_c \mathcal{C}_B$ iff $\mathcal{C}_A \subseteq_c \mathcal{C}_B$ and $\mathcal{C}_B \subseteq_c \mathcal{C}_A$.
7. $\text{Cop. } \mathcal{C}_A = \{\langle X, B \rangle \in \mathcal{C}(X) : \langle A, B \rangle \notin \mathcal{C}_A\}$
8. $\mathcal{C}_A \vee_c \mathcal{C}_B = \{\langle A \cup B, C \rangle : \langle A, C \rangle \in \mathcal{C}_A \text{ or } \langle B, C \rangle \in \mathcal{C}_B\}$
9. $\mathcal{C}_A \wedge_c \mathcal{C}_B = \{\langle A \cup B, C \rangle : \langle A, C \rangle \in \mathcal{C}_A \text{ and } \langle B, C \rangle \in \mathcal{C}_B\}$.
10. $\vee_c \mathcal{C}_{A_i} = \{\langle (\cup A_i), C \rangle : \langle A_i, C \rangle \in \mathcal{C}_{A_i} \text{ for some } i \in I\}$
11. $\wedge_c \mathcal{C}_{A_i} = \{\langle (\cup A_i), C \rangle : \langle A_i, C \rangle \in \mathcal{C}_{A_i} \text{ for each } i \in I\}$.

Definition 2.4.[10].

Let (X, δ) be a proximity space and $\{x\}, B \subseteq X$ such that $\{x\} \delta B$. Then $x_B = \{\langle \{x\}, B \rangle\}$ is called a center point in X .

Definition 2.4.[10].

Let x_B be a center point in (X, δ) and \mathcal{C}_A center set in (X, δ) . Then $x_B \in \mathcal{C}_A$ iff $x \in A$ and $\langle A, B \rangle \in \mathcal{C}_A$.

$\mathbb{P}_c(X) = \{\mathcal{C}_A : \mathcal{C}_A \text{ center set of } X\}$

Proposition 2.5.[10].

Let $\{\mathcal{C}_{A_i} : i \in I\}$ be a family of center sets in (X, δ) . Then

1. If $x_B \in \mathcal{C}_{A_i}$ for each $i \in I$, then $x_B \in \wedge_c \mathcal{C}_{A_i}$.
2. If $\exists i \in I$ such that $x_B \in \mathcal{C}_{A_i}$, then $x_B \in \vee_c \mathcal{C}_{A_i}$.
3. $\mathcal{C}_{A_1} \subseteq_c \mathcal{C}_{A_2}$ iff for each $x_B \in \mathcal{C}_{A_1} \Rightarrow x_B \in \mathcal{C}_{A_2}$.
4. $(\vee_c)_{x_B \in \mathcal{C}_A} x_B = \mathcal{C}_A$

Proposition 2.6.[10].

If $\mathcal{C}_A, \mathcal{C}_B, \mathcal{C}_C$ and $\{\mathcal{C}_{A_i} : i \in I\}$ be a center sets. Then

1. $\mathcal{C}_A \subseteq_c \mathcal{C}_B$ and $\mathcal{C}_B \subseteq_c \mathcal{C}_C \Rightarrow \mathcal{C}_A \subseteq_c \mathcal{C}_C$
2. $\mathcal{C}_{A_i} \subseteq_c \mathcal{C}_B$ for each $i \in I \Rightarrow \vee_c \mathcal{C}_{A_i} \subseteq_c \mathcal{C}_B$
3. $\mathcal{C}_B \subseteq_c \mathcal{C}_{A_i}$ for each $i \in I \Rightarrow \mathcal{C}_B \subseteq_c \wedge_c \mathcal{C}_{A_i}$
4. $\text{Co.}(\vee_c \mathcal{C}_{A_i}) = \wedge_c (\text{Cop. } \mathcal{C}_{A_i})$
5. $\text{Co.}(\wedge_c \mathcal{C}_{A_i}) = \vee_c (\text{Co. } \mathcal{C}_{A_i})$
6. $\mathcal{C}_A \subseteq_c \mathcal{C}_B \Rightarrow \text{Cop. } \mathcal{C}_B \subseteq_c \text{Cop. } \mathcal{C}_A$
7. $(\mathcal{C}_A \vee_c \mathcal{C}_B) \vee_c \mathcal{C}_C = \mathcal{C}_A \vee_c (\mathcal{C}_B \vee_c \mathcal{C}_C)$
 $(\mathcal{C}_A \wedge_c \mathcal{C}_B) \wedge_c \mathcal{C}_C = \mathcal{C}_A \wedge_c (\mathcal{C}_B \wedge_c \mathcal{C}_C)$
8. $(\mathcal{C}_A \vee_c \mathcal{C}_B) \wedge_c \mathcal{C}_C = (\mathcal{C}_A \wedge_c \mathcal{C}_B) \vee_c (\mathcal{C}_A \wedge_c \mathcal{C}_C)$
 $(\mathcal{C}_A \wedge_c \mathcal{C}_B) \vee_c \mathcal{C}_C = (\mathcal{C}_A \vee_c \mathcal{C}_B) \wedge_c (\mathcal{C}_A \vee_c \mathcal{C}_C)$
9. $\text{Cop.}(\mathcal{C}_A \vee_c \mathcal{C}_B) = \text{Cop. } \mathcal{C}_A \wedge_c \text{Cop. } \mathcal{C}_B$
 $\text{Cop.}(\mathcal{C}_A \wedge_c \mathcal{C}_B) = \text{Cop. } \mathcal{C}_A \vee_c \text{Cop. } \mathcal{C}_B$
10. $\mathcal{C}_A \vee_c \mathcal{C}_A = \mathcal{C}_A, \mathcal{C}_A \wedge_c \mathcal{C}_A = \mathcal{C}_A, \mathcal{C}_A \vee_c \mathcal{C}_\emptyset = \mathcal{C}_A$
11. $\mathcal{C}_A \vee_c \text{Co. } \mathcal{C}_A = \mathcal{C}_X, \mathcal{C}_A \wedge_c \text{Co. } \mathcal{C}_A = \mathcal{C}_\emptyset$.

Definition 2.7.[11].

Let (X, δ) be a proximity space and $\mathfrak{J}_c \subseteq \mathbb{P}_c(X)$, then \mathfrak{J}_c said to be a C-topology if

1. $\mathcal{C}_\emptyset, \mathcal{C}_X \in \mathfrak{J}_c$
2. $\{\mathcal{C}_{A_i} : i \in I\} \in \mathfrak{J}_c \Rightarrow \vee_c \{\mathcal{C}_{A_i} : i \in I\} \in \mathfrak{J}_c$.
3. $\mathcal{C}_{A_1}, \mathcal{C}_{A_2} \in \mathfrak{J}_c \Rightarrow \mathcal{C}_{A_1} \wedge_c \mathcal{C}_{A_2} \in \mathfrak{J}_c$

The triplet $(X, \delta, \mathfrak{J}_c)$ is called a C-topological space and the members of \mathfrak{J}_c are said to be C-open. \mathfrak{J}_c called indiscrete C-topology if $\mathfrak{J}_c = \{\mathcal{C}_X, \mathcal{C}_\emptyset\}$ and called discrete C-topology if $\mathfrak{J}_c \subseteq \mathbb{P}_c(X)$.

Definition 2.8.[11].

Let $(X, \delta, \mathfrak{J}_c)$ be a C-topological space. A center set \mathcal{C}_B over (X, δ) is said to be C-closed set, if there exists C-open \mathcal{C}_A such that $\text{cop.}(\mathcal{C}_A) = \mathcal{C}_B$.

Since $\text{cop.}(\mathcal{C}_A) \subseteq \mathcal{C}_X$ for each $A \subseteq X$, then we denote C-closed set by \mathcal{C}_{XA}

Proposition 2.9.[11].

Let $(X, \delta, \mathfrak{J}_c)$ be C-topological space and \mathfrak{H}_c be acollection of all C-closed sets of $(X, \delta, \mathfrak{J}_c)$. Then

1. $\mathcal{C}_X, \mathcal{C}_\emptyset \in \mathfrak{H}_c$
2. $\{\mathcal{C}_{XA_i} : i \in I\} \in \mathfrak{H}_c \Rightarrow \wedge_c \{\mathcal{C}_{XA_i} : i \in I\} \in \mathfrak{H}_c$.
3. $\mathcal{C}_{XA_1}, \mathcal{C}_{XA_2} \in \mathfrak{H}_c \Rightarrow \mathcal{C}_{XA_1} \vee_c \mathcal{C}_{XA_2} \in \mathfrak{H}_c$.

Proposition 2.10.[11].

Let $(X, \delta, \mathfrak{J}_c)$ be a C-topological space and \mathfrak{H}_c be acollection of all C-closed center sets of $(X, \delta, \mathfrak{J}_c)$. Then the following hold,

1. If \mathfrak{J}_c C-topology, then $\mathfrak{J}_c = \{\mathcal{C}_A : \text{cop.}(\mathcal{C}_A) \in \mathfrak{H}_c\}$.
2. If \mathfrak{J}_c indiscrete C-topology, then $\mathfrak{J}_c = \{\text{cop. } \mathcal{C}_{XA} : \mathcal{C}_{XA} \in \mathfrak{H}_c\}$.
3. If \mathfrak{J}_c non-indiscrete C-topology on $(X, \delta) \Rightarrow \mathcal{C} - \mathfrak{J}_c = \{\mathcal{C}_{XA'} = \text{cop. } \mathcal{C}_{XA} : \mathcal{C}_{XA} \in \mathfrak{H}_c\}$ is C-topology it is not necessary $\mathfrak{J}_c = \mathcal{C} - \mathfrak{J}_c$, But for each $\mathcal{C}_{XA'} \in \mathcal{C} - \mathfrak{J}_c$ there is $\mathcal{C}_A \in \mathfrak{J}_c$ so that $\mathcal{C}_{XA'} =_c \mathcal{C}_A$ and for each $\mathcal{C}_A \in \mathfrak{J}_c$ there is $\mathcal{C}_{XA'} \in \mathcal{C} - \mathfrak{J}_c$ so that $\mathcal{C}_A =_c \mathcal{C}_{XA'}$.

Example 2.11.[11].

Let (X, δ) be a proximity space such that $X = \{a, b, c\}$ and for each $A, B \subseteq X$ ($A \delta B \Leftrightarrow A \cap B \neq \emptyset$). Then $\mathfrak{J}_c = \{\mathcal{C}_\emptyset, \mathcal{C}_{\{a\}}, \mathcal{C}_{X \setminus \{a\}}, \mathcal{C}_X\}$ is a C-topology on (X, δ) . Hence $\mathfrak{H}_c = \{\mathcal{C}_X, \mathcal{C}_{X \setminus \{a\}}, \mathcal{C}_{X \setminus \{a, b\}}, \mathcal{C}_\emptyset\}$ is the collection of all C-closed sets. Not that $\mathcal{C}_{X \setminus \{a\}}$ is a C-closed and $\mathcal{C}_{\{a\}} \neq \text{cop. } \mathcal{C}_{X \setminus \{a\}} = \text{cop. } \{\langle X, \{b\} \rangle, \langle X, \{c\} \rangle, \langle X, \{b, c\} \rangle\} = \{\langle X, \{a\} \rangle, \langle X, \{a, b\} \rangle, \langle X, \{a, c\} \rangle, \langle X, X \rangle\} =_c \mathcal{C}_{\{a\}}$.

Definition 2.12.[11].

Let $(X, \delta, \mathfrak{J}_c)$ be a C-topological space and \mathcal{C}_B be a center set. Then the C-closure of \mathcal{C}_B , denoted by $cl_c(\mathcal{C}_B)$ is,

$cl_c(\mathcal{C}_B) = \wedge_c \{\mathcal{C}_{XA} : \mathcal{C}_{XA} \text{ C-closed and } \mathcal{C}_B \subseteq_c \mathcal{C}_{XA}\}$

Definition 2.13.[11].

Let $(X, \delta, \mathfrak{J}_c)$ be a C-topological space, \mathcal{C}_A be a center set and x_B be a center point. Then \mathcal{C}_A is said to be a C-neighborhood of x_B , if there exists a C-open set $\mathcal{C}_{A'}$ such that $x_B \in_c \mathcal{C}_{A'} \subseteq_c \mathcal{C}_A$.

Proposition 2.14.[11].

Let $(X, \delta, \mathfrak{J}_c)$ be a C-topological space. Then

1. each center point x_B has a C-neighborhood.
2. if \mathcal{C}_A and $\mathcal{C}_{A'}$ are C-neighborhoods of some x_B , then $\mathcal{C}_A \wedge_c \mathcal{C}_{A'}$ is also a C-neighborhood of x_B .
3. if \mathcal{C}_A is a C-neighborhood of x_B and $\mathcal{C}_A \subseteq_c \mathcal{C}_{A'}$, then $\mathcal{C}_{A'}$ is also a C-neighborhood of x_B .



Definition 2.15.[11].

Let $(X, \delta, \mathfrak{J}_C)$ be a \mathcal{C} -topological space, \mathcal{C}_A be a center set and x_B be a center point. Then x_B is said to be an \mathcal{C} -interior point of \mathcal{C}_A , if there exists a \mathcal{C} -open set $\mathcal{C}_{A'}$ such that $x_B \in_C \mathcal{C}_{A'} \leq_C \mathcal{C}_A$.

Definition 2.16.[11].

Let $(X, \delta, \mathfrak{J}_C)$ be a \mathcal{C} -topological space and \mathcal{C}_A be a center set. Then the \mathcal{C} -interior of \mathcal{C}_A , denoted by $\text{int}_C(\mathcal{C}_A)$ is,

$$\text{int}_C(\mathcal{C}_A) = \bigvee_C \{ \mathcal{C}_{A'} : \mathcal{C}_{A'} \text{ } \mathcal{C}\text{-open and } \mathcal{C}_{A'} \leq_C \mathcal{C}_A \}$$

III. C-IDEAL SPACE

In this section, we shall recall some basic concepts about "ideal" in topological space.

Definition 3.1.

Let (X, δ) be a proximity space. A family \mathcal{J}_C of subsets center sets is an " \mathcal{C} -ideal" if

1. $\mathcal{C}_A, \mathcal{C}_B \in \mathcal{J}_C$ implies $\mathcal{C}_A \vee_C \mathcal{C}_B \in \mathcal{J}_C$
2. $\mathcal{C}_A \in \mathcal{J}_C$ and $\mathcal{C}_B \leq_C \mathcal{C}_A$ implies $\mathcal{C}_B \in \mathcal{J}_C$.
3. $\mathcal{C}_X \notin \mathcal{J}_C$.

Theorem 3.2.

Let $\{(\mathcal{J}_C)_\alpha : \alpha \in \Delta\}$ be any \mathcal{C} -ideals family on proximity space (X, δ) . Then $\mathcal{J}_C = \bigcap \{(\mathcal{J}_C)_\alpha : \alpha \in \Delta\}$ is also \mathcal{C} -ideal on (X, δ) .

Proof.

1. Let \mathcal{C}_A and \mathcal{C}_B in \mathcal{J}_C . Then Let \mathcal{C}_A and \mathcal{C}_B in $(\mathcal{J}_C)_\alpha$, for each $\alpha \in \Delta$. Since $(\mathcal{J}_C)_\alpha$ is an \mathcal{C} -ideal on (X, δ) , then $\mathcal{C}_A \vee_C \mathcal{C}_B \in (\mathcal{J}_C)_\alpha$, for each $\alpha \in \Delta$. So $\mathcal{C}_A \vee_C \mathcal{C}_B \in \mathcal{J}_C$.
2. Let $\mathcal{C}_A \in \mathcal{J}_C$ and $\mathcal{C}_B \leq_C \mathcal{C}_A$. Then $\mathcal{C}_A \in (\mathcal{J}_C)_\alpha$ for each $\alpha \in \Delta$. Since $(\mathcal{J}_C)_\alpha$ is an ideal on (X, δ) , $\mathcal{C}_B \leq_C \mathcal{C}_A$, then $\mathcal{C}_B \in (\mathcal{J}_C)_\alpha$ for each $\alpha \in \Delta$. So $\mathcal{C}_B \in \mathcal{J}_C$.

Remark 3.3.

1. The union of two \mathcal{C} -ideals on (X, δ) is not necessary \mathcal{C} -ideal, for example: Let (X, δ) be a proximity space where $X = \{x, y\}$ and $(\forall A, B \subseteq X, A\delta B \Leftrightarrow A \cap B \neq \emptyset)$, then $\mathcal{J}_{C1} = \{\mathcal{C}_\emptyset, \mathcal{C}_{\{x\}}\}$ and $\mathcal{J}_{C2} = \{\mathcal{C}_\emptyset, \mathcal{C}_{\{y\}}\}$ be \mathcal{C} -ideals $\mathcal{J}_{C1} \cup \mathcal{J}_{C2} = \{\mathcal{C}_\emptyset, \mathcal{C}_{\{x\}}, \mathcal{C}_{\{y\}}\}$ is not an \mathcal{C} -ideal.
2. The intersection of all \mathcal{C} -ideals on (X, δ) is the \mathcal{C} -ideal $\{\mathcal{C}_\emptyset\}$.

Example 3.4.

Let (X, δ) be a proximity space. Then $\mathcal{J}_C = \{\mathcal{C}_A : \mathcal{C}_A \text{ is finite center of } X\}$ is an \mathcal{C} -ideal on (X, δ) called finite \mathcal{C} -ideal.

Definition 3.5.

Let (X, δ) be a proximity space. A family \mathcal{J}_{C0} of subsets center sets is an " \mathcal{C} -ideal base" if,

1. $\mathcal{C}_X \notin \mathcal{J}_{C0}$.
2. If $\mathcal{C}_A \in \mathcal{J}_{C0}$ and $\mathcal{C}_B \in \mathcal{J}_{C0}$, then there exists $\mathcal{C}_C \in \mathcal{J}_{C0}$ such that $\mathcal{C}_A \vee_C \mathcal{C}_B \leq_C \mathcal{C}_C$.

Observe that if $\mathcal{C}_A \vee_C \mathcal{C}_B \in \mathcal{J}_{C0}$, for each \mathcal{C}_A and \mathcal{C}_B in \mathcal{J}_{C0} , then \mathcal{J}_{C0} is an \mathcal{C} -ideal base on X and so any \mathcal{C} -ideal on X is \mathcal{C} -ideal base.

Example 3.6.

Let (X, δ) be a proximity space where $X = \{x, y\}$ and $(\forall A, B \subseteq X, A\delta B \Leftrightarrow A \cap B \neq \emptyset)$, then $\mathcal{J}_{C0} = \{\mathcal{C}_{\{x\}}, \mathcal{C}_{\{y\}}, \mathcal{C}_{\{x\}} \vee_C \mathcal{C}_{\{y\}}\}$ is an \mathcal{C} -ideal base.

Example 3.7.

Let \mathcal{J}_C be an \mathcal{C} -ideal on (X, δ) and \mathcal{C}_A center set, such that $\mathcal{C}_A \vee_C \mathcal{C}_B \neq \mathcal{C}_X$ for each $\mathcal{C}_B \in \mathcal{J}_C$. Then, $\mathcal{J}_{C0} = \{\mathcal{C}_A \vee_C \mathcal{C}_B : \mathcal{C}_B \in \mathcal{J}_C\}$ is an \mathcal{C} -ideal base on X .

Solution.

Let \mathcal{C}_{K1} and \mathcal{C}_{K2} in \mathcal{J}_{C0} , then there exists \mathcal{C}_{B1} and \mathcal{C}_{B2} in \mathcal{J}_C such that $\mathcal{C}_{K1} = \mathcal{C}_A \vee_C \mathcal{C}_{B1}$ and $\mathcal{C}_{K2} = \mathcal{C}_A \vee_C \mathcal{C}_{B2}$. Then $\mathcal{C}_{K1} \vee_C \mathcal{C}_{K2} = \mathcal{C}_A \vee_C (\mathcal{C}_{B1} \vee_C \mathcal{C}_{B2}) \in \mathcal{J}_{C0}$ because $\mathcal{C}_{B1} \vee_C \mathcal{C}_{B2} \in \mathcal{J}_C$. So that \mathcal{J}_{C0} is an \mathcal{C} -ideal base.

Proposition 3.8.

Let \mathcal{J}_{C0} be an \mathcal{C} -ideal base on (X, δ) , then $\mathcal{J}_C = \{\mathcal{C}_A : \mathcal{C}_A \leq_C \mathcal{C}_B \text{ for some } \mathcal{C}_B \in \mathcal{J}_{C0}\}$ is an \mathcal{C} -ideal on (X, δ) generated by \mathcal{J}_{C0} .

Proof.

- Let \mathcal{J}_{C0} be an \mathcal{C} -ideal base on (X, δ) .
1. Let $\mathcal{C}_A \in \mathcal{J}_C$ and $\mathcal{C}_B \leq_C \mathcal{C}_A$. Then there exists $\mathcal{C}_C \in \mathcal{J}_{C0}$ lo such that $\mathcal{C}_B \leq_C \mathcal{C}_C$, so $\mathcal{C}_A \leq_C \mathcal{C}_C$. Thus $\mathcal{C}_B \in \mathcal{J}_C$.
 2. Let $\mathcal{C}_A \in \mathcal{J}_C$ and $\mathcal{C}_B \in \mathcal{J}_C$. Then there exists $\mathcal{C}_C \in \mathcal{J}_{C0}$, and $\mathcal{C}_D \in \mathcal{J}_{C0}$ such that $\mathcal{C}_A \leq_C \mathcal{C}_C$ and $\mathcal{C}_B \leq_C \mathcal{C}_D$.

Since \mathcal{J}_{C0} is an \mathcal{C} -ideal base, then there exists $\mathcal{C}_E \in \mathcal{J}_{C0}$, such that $\mathcal{C}_C \vee_C \mathcal{C}_D \leq_C \mathcal{C}_E$. So $\mathcal{C}_A \vee_C \mathcal{C}_B \leq_C \mathcal{C}_E$. Therefore $\mathcal{C}_A \vee_C \mathcal{C}_B \in \mathcal{J}_C$. From 1 and 2, \mathcal{J}_C is an \mathcal{C} -ideal on (X, δ) .

Proposition 3.9.

Let (X, δ) be a proximity space and $Y \subseteq X$. If \mathcal{J}_{C0} , is an \mathcal{C} -ideal base on (Y, δ) , then it's \mathcal{C} -ideal base on (X, δ) .

Proof.

Direct by using definition of ideal base.

Corollary 3.10.

Let (X, δ) be a proximity space and $Y \subseteq X$. If \mathcal{J}_C , is an \mathcal{C} -ideal on (Y, δ) , then it's \mathcal{C} -ideal on (X, δ) .

Definition 3.11.

Let \mathcal{J}_C and \mathcal{J}_E be two \mathcal{C} -ideals on the proximity space (X, δ) . Then \mathcal{J}_C is said to be "finer than" \mathcal{J}_E if and only if $\mathcal{J}_C \leq_C \mathcal{J}_E$.

Example 3.12.

Let (X, δ) be a proximity space where $X = \{1,2\}$ and $(\forall A, B \subseteq X, A\delta B \Leftrightarrow A \cap B \neq \emptyset)$, . Then $\mathcal{J}_{C1} = \{\mathcal{C}_\emptyset, \mathcal{C}_{\{1\}}\}$ and $\mathcal{J}_{C2} = \{\mathcal{C}_\emptyset, \mathcal{C}_{\{2\}}, \mathcal{C}_{\{1\}} \vee_C \mathcal{C}_{\{2\}}\}$ are \mathcal{C} -ideals on (X, δ) and \mathcal{J}_{C2} finer than \mathcal{J}_{C1} .

Remark 3.13.

Let (X, δ) be a proximity space. Any \mathcal{C} -ideal on (X, δ) is finer than $\{\mathcal{C}_\emptyset\}$.

Theorem 3.14.

Let (X, δ) be a proximity space and let \mathcal{J}_C be an \mathcal{C} -ideal on (X, δ) such that $\bigvee_{\mathcal{C}_B \in \mathcal{J}_C} \mathcal{C}_B = \mathcal{C}_X$. Then \mathcal{J}_C is finer than the finite \mathcal{C} -ideal on (X, δ) .

Proof.

Let (X, δ) be the finite C-ideal on (X, δ) . To show that $J_C \subseteq J_e$. Suppose if possible $J_C \not\subseteq J_e$.

Then there exists $C_A \in J_e$ such that $C_A \notin J_C$. Then C_A is finite center set of (X, δ) , Let $C_A = \{ \langle A, K_1 \rangle, \langle A, K_2 \rangle, \dots, \langle A, K_n \rangle \}$.

Now $\bigvee_{C_B \in J_C} C_B = C_X$. Then $\langle B_i, K_i \rangle \in C_{B_i}$ for some $C_{B_i} \in J_C, (i = 1, \dots, n)$. Since J_e is an C-ideal, $C_D = \bigvee_{i=1}^n C_{K_i} \in J_e$.

Thus, $\langle \bigcup_{i=1}^n B_i, K_i \rangle \in C_D$ element of $\{i = 1, 2, \dots, n\}$. Hence $C_A \preceq_C C_D$. Since J_e is an C-ideal, implies $C_A \in J_e$.

But this is a contradiction with $C_A \notin J_C$. Hence J_C must be finer than the finite C-ideal.

Definition 3.15.

Let J_C be an C-ideal on (X, δ) . Then J_C is said to be "maximal C-ideal" on (X, δ) if and only if J_C is not contained in any other C-ideal on (X, δ) . i.e. J_C is a maximal C-ideal on (X, δ) if and only if for every C-ideal J_e on (X, δ) such that $J_C \subseteq J_e$, then $J_C = J_e$.

Theorem 3.16.

Let (X, δ) be a proximity space. Every C-ideal on (X, δ) is contained in a maximal C-ideal.

Proof.

Let J_C be any C-ideal on (X, δ) and let W be the class of all C-ideals on (X, δ) containing J_C .

Then W is non-empty because $J_C \in W$. Also, W is partially ordered by the inclusion relation \subseteq .

Now let K be linearly ordered subset of W . Then by definition of linear ordering for any two members J_{C1}, J_{C2} of K , we have either $J_{C1} \subseteq J_{C2}$ or $J_{C2} \subseteq J_{C1}$.

Let $S = \bigcup \{ (J_C)_\gamma : (J_C)_\gamma \in K \}$. To show that S is an C-ideal on (X, δ) .

1. Since each $(J_C)_\gamma$ is an C-ideal, we have $C_X \notin (J_C)_\gamma$, for each an C-ideal $(J_C)_\gamma \in S$ and so $C_X \notin S$.
2. Let $C_A \in S$ and $C_B \preceq_C C_A$. Then $C_A \in (J_C)_\gamma$ for some $(J_C)_\gamma \in S$. Since $(J_C)_\gamma$ is an C-ideal, then $C_B \in (J_C)_\gamma$. It follows that $C_B \in S$.
3. Let $C_A \in S$ and $C_B \in S$. Then $C_A \in (J_C)_\gamma$, and $C_B \in (J_C)_\alpha$ for some $(J_C)_\gamma, (J_C)_\alpha \in S$.

Since S is linearly ordered, we have either $(J_C)_\gamma \subseteq (J_C)_\alpha$ or $(J_C)_\alpha \subseteq (J_C)_\gamma$. Hence both C_A and C_B belong either to $(J_C)_\gamma$ or to $(J_C)_\alpha$ and so $C_A \vee_C C_B$ belongs either to $(J_C)_\gamma$ or to $(J_C)_\alpha$. It follows that $C_A \vee_C C_B \in S$.

Further S is finer than every member of K and so S is upper bound of K .

Thus, we have shown that W is a non-empty partially ordered set in which every linearly ordered subset has an upper bound. Hence by Zorn's lemma W contains a maximal element J_C . This maximal element is by definition, maximal ideal on (X, δ) containing J_C .

Proposition 3.17.

Let (X, δ) be a proximity space. An C-ideal J_C on (X, δ) is a maximal C-ideal if and only if for each center set C_A of X , then either $C_A \in J_C$ or $cop.(C_A) \in J_C$.

Proof.

If $cop.(C_A) \notin J_C$, then $C_A \vee_C C_B \neq C_X$ for each $C_B \in J_C$, because if there exists $C_B \in J_C$ such that $C_A \vee_C C_B = C_X$,

then $cop.(C_A) \preceq_C C_B$ and so by definition C-ideal we have $cop.(C_A) \in J_C$ contradiction.

Let J_C be an C-ideal generated by C-ideal base $\{C_A \vee_C C_B : C_B \in J_C\}$ then

$$J_C = \{C_D : C_D \preceq_C C_A \vee_C C_B, \text{ for some } C_B \in J_C\}$$

Since $C_A \preceq_C C_A \vee_C C_B$ for each $C_B \in J_C$, then $C_A \in J_C \dots (1)$.

To show that $J_C \subseteq J_e$

Let $C_K \in J_e$. Since $C_K \preceq_C C_A \vee_C C_B$, then $C_K \in J_C$ and we have $J_e \subseteq J_C$. But J_C is maximal C-ideal, then $J_C = J_e$. By (1) $C_A \in J_C$.

Conversely. Let, J_C be an C-ideal on (X, δ) and $J_e \subseteq J_C$. To prove that $J_C \subseteq J_e$. Suppose $J_C \not\subseteq J_e$, then there exists $C_B \in J_C$ such that $C_B \notin J_e$.

Then by hypothesis $cop.(C_B) \in J_e$. But $J_C \subseteq J_e$, so $cop(C_B) \in J_C$. Thus $C_B \vee_C cop.(C_B) = C_X \in J_C$

But this contradiction because $C_X \notin J_C$, so that $J_C \subseteq J_e$ and we have $J_C = J_e$. Therefore, that J_C is maximal C-ideal.

Theorem 3.18.

Let (X, δ) be a proximity space. An C-ideal J_C on X is maximal C-ideal if and only if J_C contains all those center sets which $C_A \vee_C C_B \neq C_X$ for each $C_B \in J_C$.

Proof.

Let J_C be a maximal C-ideal and let $C_A \preceq_C C_X$ such that $C_A \vee_C C_B \neq C_X$ for each $C_B \in J_C$. Let

$$J_e = \{C_D : C_D \preceq_C C_A \vee_C C_B \text{ for each } C_B \in J_C\}$$

Observe that $J_C \subseteq J_e$, because $C_B \preceq_C C_A \vee_C C_B$ for each $C_B \in J_C$. To show that J_C is C-ideal on (X, δ) .

1. To prove $C_X \notin J_e$. Let $C_D \in J_e$, then $C_D \in \preceq_C C_A \vee_C C_B$ for each $C_B \in J_C$. But $C_A \vee_C C_B \neq C_X$ for each $C_B \in J_C$. So $C_D \neq C_X$. Therefore, $C_X \notin J_e$.
2. Let $C_D \in J_C$ and $C_K \preceq_C C_D$, then $C_D \preceq_C C_A \vee_C C_B$ for each $C_B \in J_C$. So that $C_K \preceq_C C_D \preceq_C C_A \vee_C C_B$. Hence $C_K \in J_C$.
3. Let $C_{D1}, C_{D2} \in J_C$, then $C_{D1} \preceq_C C_A \vee_C C_B$ and $C_{D2} \preceq_C C_A \vee_C C_B$ for each $C_B \in J_C$, so $C_{D1} \vee_C C_{D2} \preceq_C C_A \vee_C C_B$. Thus $C_{D1} \vee_C C_{D2} \in J_C$ for each. Therefore J_C is an C-ideal on (X, δ) . Since J_C is maximal C-ideal, then $J_C = J_e$. Since $C_A \preceq_C C_A \vee_C C_B$ for each $C_B \in J_C$ so that $C_A \in J_C$ so also $C_A \in J_e$.

Conversely. Let J_C be an C-ideal satisfying the condition and let J_e be an C-ideal on (X, δ) such that $J_C \subseteq J_e$. To prove, $J_C \subseteq J_e$, let $C_A \in J_C$, then $C_A \vee_C C_B \neq C_X$ for each $C_B \in J_C$. Since $J_C \subseteq J_e$, then $C_A \vee_C C_B \neq C_X$ for each $C_B \in J_C$, so $C_A \in J_e$ and so also $J_C \subseteq J_e$. Thus $J_C = J_e$ and we have J_C is a maximal C-ideal on (X, δ) .

IV. CONCLUSION

In the current work, we continue to study the properties of C-ideal via C-topology. We also offer C-turning (bench) points and have established many interesting properties. We trust that the discoveries in this paper will enable analyst to upgrade and advance further investigation on the C-ideal to complete a general system for their applications in down to practical life.



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