

# An Implementation of Harmonic Suppression in 3 Φ Inverter using SVPWM



M.Selvaperumal, D.Kirubakaran

**Abstract:** An inverter is used to transform into permanent DC potential to AC potential. It SVPWM step technique is used as a flexible result as it is used DC bus potential more excellently, the plasticization is achieved Spartan -three discipline-programmable gate array board utilizing hardware elaborately pictures que language (VHDL)FIELD programmable gate array allots a appreciable peak stage plane/implementation instruments named as XILINX. Them effectively MOSFET is the switching instruments utilised in 3 phase inverter.

**Keywords:** XILINX, FIELD PROGRAMMABLE GATE ARRAY, MOSFET, 3 Phase Inverter .

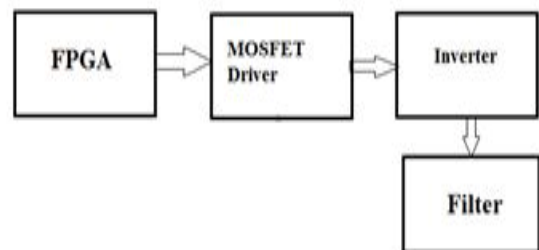
## I. INTRODUCTION

3Φ potential Pulse with modulation dc to ac converter are abundantly utilized for companies' uses contained by procedures wherever 3 Φ induction motors are utilized during different speed activation in addition to during electric vehicle production. The speed limit of three phase induction motor has been surface intricate compare to dc coast but recent development in Pulse with modulation and Metal Oxide Semiconductor Field Effect Transistor is helped to limited. In this paper space vector with pulse with modulation algorithm is installed on the Spartan kit the gives programmable field programmable gate array relied. SVPWM modulation technique installation for 3 phase SOC surroundings for designing modern digital application particular integrated circuit controller for Specific applications, since it is a hardware description language, the field-programmable gate array output is provided to the driver in the same way.

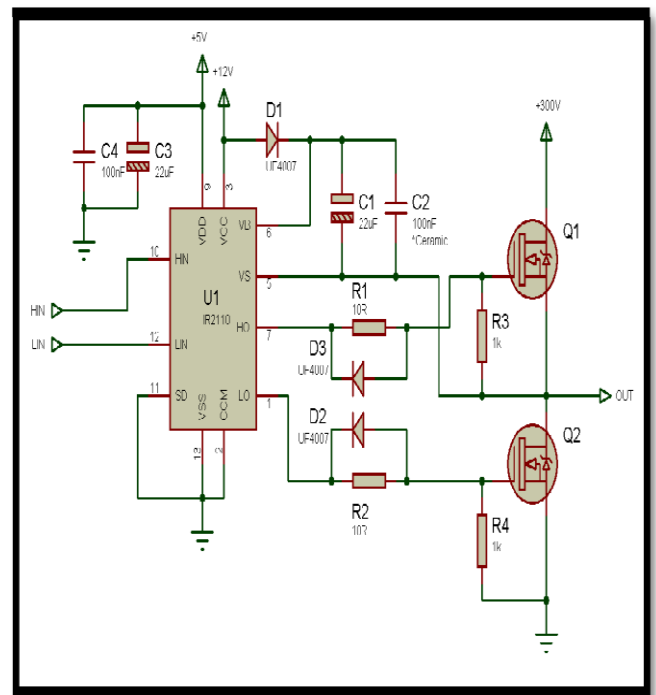
## II. CIRCUIT DESCRIPTION

An output potential from an inverter can be adjusted by means of working towards a restrict at the switching length of MOSFETs within the inverter. Here a hard and fast direct modern-day input capability is given to the inverter and

square wave output potential is acquired via transistors. The triangular wave feed to sieve exposed can supply a resultant sin signal which be capable of be specified for program such as powering of asynchronous machine. That is one of the not unusual methods of controlling the output ability named as PWM manipulate. Most of the pulse with modulation used in Sine wave pulse width modulation is previously predictable with SVPWM becoming popular.



Block diagram for 3 phase inverter



### Three Half Bridge Inverter

There are unique algorithms applied to replace the MOSFETs inside the inverter circuits. Most of the SVPWM schemes have been found out widely in the iteration. The uses of each modulation strategy are to reduce the switching losses and elaborate bus utilisation losses harmonics losses and still achieve specific control.

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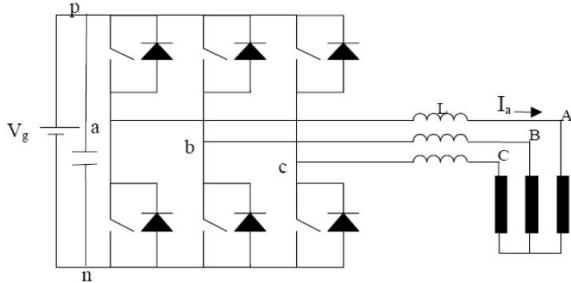
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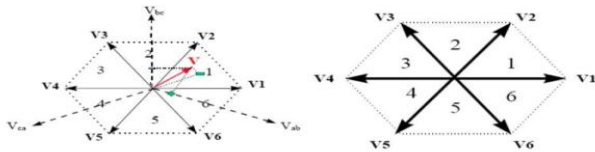
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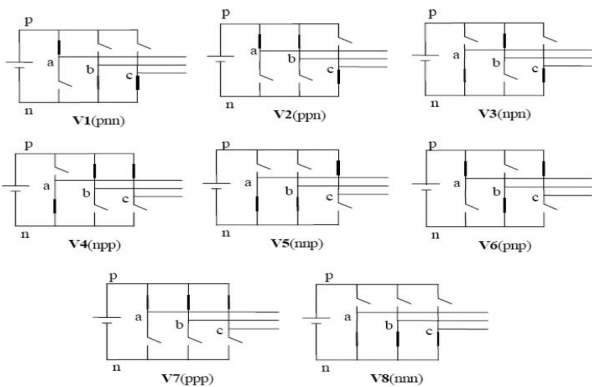
Here firing pulse input DC potential and output AC potential both lines and phase are main bus focussed parameter 1<sup>st</sup> objective is to transform 3-axes time-variant parameters to 2-axes time-invariant parameters ability equation in A, B, C reference body parameters may be transformed into desk-bound reference body that compressed direct and quadrature parameters.



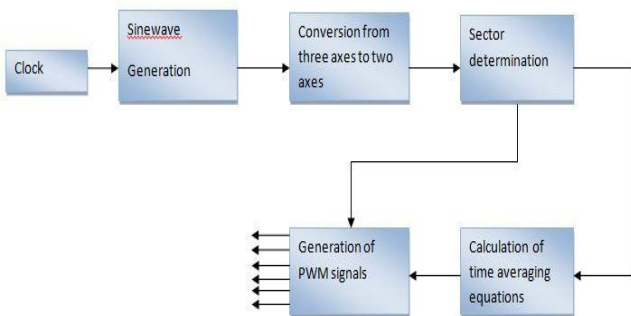
The continuous vectors are V1, V2, V3, V4, V5 and V6 shapes the axis of hexagonal as illustrate in diagram supply to his 3 phase consumed. The angle between successive vector components is 60. The two zero vectors (V0 & V7) deliver 0 voltages to the load preliminary circumstance. The 8th vectors are called in base area vectors are represented through V0 to V7. The equal conversion technique may be carried out to get voltage to set the expected reference voltage vector  $V_{ref}$  in the d-q plane. The time of the distance vector method almost the reference voltage vector the use of the 8 switching sample.



## Switching sample strategies



Switch state and d-q axes



Block Diagram of SVPWM

## Steps for the realization of the algorithm:

- (i) Analysis  $E_a, E_b, E_c$  from the cause regulator.
- (ii) Evaluation d, q axis from a, b, and c.
- (iii) Evaluation of the world variety in which the vector lies.
- (iv) Evaluation of time duration  $T_0, T_1,$  and  $T_2$ .
- (v) Analysis of the switching time of each one transistor (S1 to S6).

### Step 1

As stated over the abc orientation body i.e. three-axes Potentials be on the road to subsist transformed into two axes (d-q reference frame. by using derivation.

$$E_d = (2E_a - E_b - E_c)/3$$

$$E_q = (E_b - E_c)/3^2$$

Department via  $3^2$  and '3' is a common term in both equations and hence can be kept apart. Department is a mild composite even as coding in VHDL .

$$Y_d = 2E_a - E_b - E_c$$

$$Y_q = E_b - E_c$$

$$\text{where } E_d = Y_d/3$$

$$\text{where } E_q = Y_q/3^2$$

### Step 2

motive a place relies upon lone on the sign of  $Y_d$  and  $Y_q$  as in keeping with the following guidelines. Reason of the sectors can be achieved by purely read-via three situations:

situation 1: a mark of  $Y_d$  stipulation 2: the mark of  $Y_q$

clause3:  $|Y_d| > |Y_q/2|$

Do that part through easy mixture logic circuits that have been implemented. First, execute condition 1 and then stipulation 2 is applied in the hold we implement Expression  $Y_q/2$  with Shift to the proper one bit.

The regulations to discover sectors determined on: statute 1:

if ( $X_d > \text{zero} \ \& \ X_q > \text{zero} \ \& \ |X_d| > |X_q/2|$ ) area-1

statute 2: if ( $X_d > 0 \ \& \ X_q > 0 \ \& \ |X_d| < |X_q/2|$ ) quarter-2 OR if ( $X_d < 0 \ \& \ X_q > \text{zero} \ \& \ |X_d| < |X_q/2|$ ) quarter-2

statute three: if ( $X_d < 0 \ \& \ X_q > \text{zero} \ \& \ |X_d| > |X_q/2|$ ) sector-3

statute 4: if ( $X_d < 0 \ \& \ X_q < 0 \ \& \ |X_d| > |X_q/2|$ ) quarter-4

statute five: if ( $X_d > \text{zero} \ \& \ X_q < 0 \ \& \ |X_d| < |X_q/2|$ ) area-5 OR

if ( $X_d < 0 \ \& \ X_q < \text{zero} \ \& \ |X_d| < |X_q/2|$ ) Sector-5

statute 6: if ( $X_d > \text{zero} \ \& \ X_q < 0 \ \& \ |X_d| > |X_q/2|$ ) quarter-6

### Step 3

If (sector=1)  $\Rightarrow T_n = X_d$

shift\_to\_right( $X_q$ ),  $T_{n+1} = X_q$ ,  $T_0 = \sqrt{3} - T_n + T_{n+1}$

If (region=2)  $\Rightarrow T_n = X_d + \text{shift\_to\_right}(X_q)$ ,  $T_{n+1} = \text{shift\_to\_ri}$

ght( $X_q$ ) -  $X_d$ ,  $T_0 = \sqrt{3} - T_n + T_{n+1}$

If (zone=3)  $\Rightarrow T_n = X_q$ ,  $T_{n+1} = -X_d \text{ shift\_to\_right}(X_q)$ ,

$T_0 = \sqrt{3} - T_n + T_{n+1}$

If (zone=4)  $\Rightarrow T_n = -X_d + \text{shift\_to\_right}(X_q)$ ,  $T_{n+1} = -X_q$ ,

$T_0 = \sqrt{3} - T_n + T_{n+1}$

If (sector=five)  $\Rightarrow T_n = -X_d - \text{shift\_to\_right}(X_q)$ ,

$T_{n+1} = X_d \text{ shift\_to\_right}(X_q)$ ,  $T_0 = \sqrt{3} - T_n + T_{n+1}$

If (region=6)  $\Rightarrow T_n = -X_q$ ,  $T_{n+1} = X_d + \text{shift\_to\_right}(X_q)$ ,

$T_0 = \sqrt{3} - T_n + T_{n+1}$

### Step 4

A time period of any Pulse with Modulation pulse is the reliant number of a quarter and switching times  $T_0, T_1,$  and  $T_2$  so that you can put into effect Pulse with Modulation pulse generation use a counter.

Rangeofcounter

$$(T_0/2 + T_2 + T_1 + T_0/2 + T_0/2 + T_1 + T_2 + T_0/2 = 2xT_0 + 2xT_1 + 2xT_2)$$

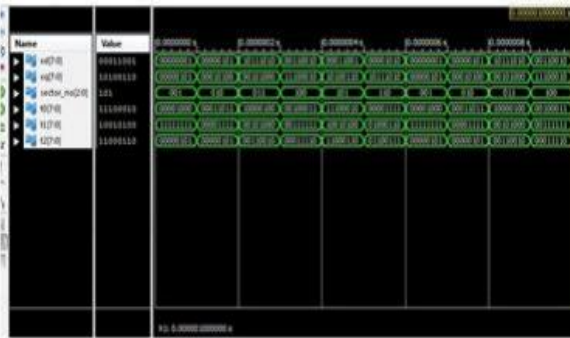
(instance period) now comparative to wide variety of sector and counter.

Pulse with Modulation pulse is "zero" or "1" (low or high).

For area 1 and a pair of range of counter is 1 to  $(2xT_0 + 2xT_1 + 2xT_2)$

```

:If(area=1)[If(counter=T0/2)=>
PWM_A='1',PWM_B='0',PWM_C='0';
If(counter=T0/2+T1)=>
PWM_A='1',PWM_B='1',PWM_C='0';
If(counter=T0/2+T1+T2)=>PWM_A='1',
PWM_B='1',PWM_C='1';
If(counter=T0+T1+T2)=>
PWM_A='1',PWM_B='1',PWM_C='1';
If(counter=T0+T1+T2+T0/2)=>
PWM_A='1',PWM_B='1',PWM_C='zero';
If(counter=T0+T1+2T2+T0/2)=>
PWM_A='1',PWM_B='0',PWM_C='0';
If(counter=T0+2T1+2T2+T0/2)
    
```



(4) Simulation of time averaging equation



(5) Simulation of generation of PWM signals

```

PWM_A='0',PWM_B='0',PWM_C='zero';
If(counter=2T0+2T1+2T2)=>
PWM_A='0',PWM_B='zero',PWM_C='0';
    
```

**III. ALGORITHM FOR SVPWM:**

The step by step procedure is applied in VHDL(Very excessive-speed included Circuit hardware Description Language) are a hardware description language utilized in digital layout automation to describe digital and combined-signal systems inclusive of field-programmable gate arrays and incorporated circuits and applied on field programmable gate array there are principal distinction among conventional programming language and hardware Description Language.

Step 1: here the traditional language is numerous strategies compared to hardware Description Language.

Step 2: Always HDL programs runs but traditional programming language if commanded.

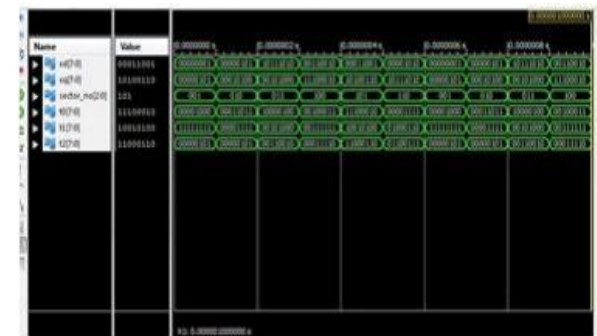
Step 3: Experimental result SVPWM was executed in VHDL using XILINX ISE9.21 the experiment of the same was verified using Spartan to field programmable gate array kit.



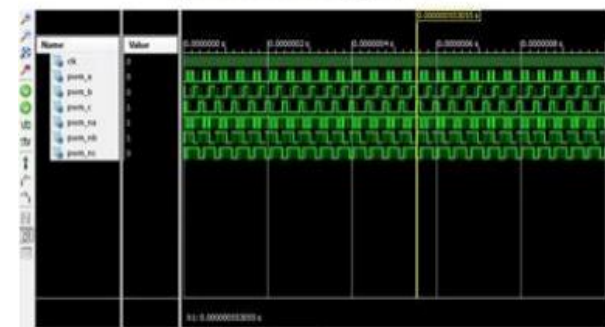
(1) Simulation of look up table for generating sine values



(2) Simulation of three-to-two axis conversion



(4) Simulation of time averaging equation



(5) Simulation of generation of PWM signals





(6) Simulation of SVPWM module



(7) PWM pulses observation on DSO

## IV CONCLUSION

As the set of rules coded in VHDL are applied on field programmable gate array. It gives fundamentals for utility-special design of IC fabrication for space vector modulation is implemented in the configuration among impartial network toolbar of mat lab. The neutral network could assist breaking sample in case of a controller utilized in electrical vehicle. The three phase induction motor speed variant design by the space vector modulation as well as inverter switches strategies' based on area vector pulse with modulation.

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## AUTHORS PROFILE



**Mr.M.Selvaperumal** completed his Bachelors of Engineering Degree in Electrical and Electronics Engineering from Madras University in the year 2002 and Masters of Engineering in Power Electronics and Industrial Drive systems from Sathyabama University, Chennai in the year 2005. Currently he is a research scholar in Electrical Engineering of Sathyabama University. His full fledged interest is on the subjects asymmetrical cascade 3 phase 9 level inverter circuits.



**Dr.D.Kirubakaran** secured his Doctor of Philosophy from Anna University, Chennai in the year of 2012. His research areas includes power electronics converter, 3 phase inverters, and power electronics drives systems. He has also presided as the chairperson in various national and international conferences held in India and abroad. Dr.D.Kirubakaran has published in more than 96 research articles in the leading international journals. Also he is a member of various professional societies like IEEE, IETE, ISTE, IEI etc.