



# Minimize of Harmonic Distortion and Power Quality Analisis using a New Discontinuous Svpwm of Multilevel Inverer for Indestrial Deives

K.RamaGandhi, K.Harinadha Reddy

**Abstract:** *The paper proposed space vector pulse width modulation is comparing the author Ramakrishna maheswari and Joan Nicolas reference in the paper. In speed control strategies for the recruitment engine has driven their use in nearly every single electrical drive. For better execution the high control acceptance machines are planned at medium voltage (mv) rating. In the event that single power semiconductor switch is legitimately associated with medium voltage, it might harm. Too, customary inverters produce high recurrence normal mode voltage. Staggered inverter is an elective answer for high control and medium voltage A.C. drive. It begins from three levels. The staggered inverter topology blends a sinusoidal voltage from a few degrees of voltages got from capacitor voltage sources. In this paper, a way to deal with diminish total harmonic distortion utilizing four level diode clamped staggered inverter (DCMLI) for three stage enlistment engine drive is proposed.*

**Keywords:** Space Vector Pulse Width Modulation, Diode Clamped, DC-AC Converters.

## I. INTRODUCTION

Inverters are broadly utilized in factor speed drives in light of their capacity to control the greatness and recurrence of the yield voltage. The synchronous exchanging of the arrangement associated gadgets creates voltage with a high dv/dt at the yield terminal of the inverter [2]. Consequently, in the uses of ac engine drives, the examination of the basic mode electrical energy is significant. A can diminish just as wipe out lessens symphonious twisting at low exchanging recurrence. along with the setups of staggered inverter, 4-level diode clamped staggered inverters have some development includes thus recreation is performed utilizing and reproduction results demonstrate that it lessens total symphonious contortion. Staggered inverter innovation has developed as of late as a significant option in the zone of high-control medium electrical energy vitality control.

Today, it is difficult to interface a solitary power semiconductor switch straight forwardly to average electrical energy lattices. Symphonious twisting is high for traditional inverter. Consequently, one more group of diode clasped staggered inverters has risen as the answer for working with higher electrical energy levels and lower symphonious mutilation [1]. Rodriguez and examined a few staggered inverter topologies to build the power conveyed to the heap and to improve the nature of the electrical energy [2]. In this paper, we probable four level diode clamped energy source inverter. This clamping diode can deliver extra electrical energy level that lessens the symphonious mutilation. A various beat width adjustment (PWM) procedures have been talked about to control the inverter [3]. Among these balance methods for a staggered inverter, SVPWM is the a big amount renowned strategy because of their interesting attributes, for example, legitimately utilizing the control changeable, improving dc interface electrical energy usage, decreasing recompense misfortunes and THD, the space vector graph comprises of six parts for any level inverter. Every division contains  $(m+1)$  triangles where m is the calculate of levels wherein the position vector can be situated inside any of these triangles. An exchange vector connecting a range of exchanging states speaks to the vertices of every triangle. There are  $m^3$  exchange states for m-level inverter. The on time conditions of SVPWM execute the exchanging conditions of the triangle. The presentation of the inverter fundamentally relies upon the determination of these exchanging states [5]. Triangle numbers, exchanging states increment with the development of level that makes computational intricacy as far as on time counts. There are different break vector calculations that demonstrate the improved execution. Among them some are referenced with their restrictions. Vector framework reliant on SVPWM calculation that needs a few lattice changes, absences of customary agreement of deciding the exchanging states and is unacceptable for invariable usage [6] technique projected with two level on time figuring will bring regarding absolute estimate higher than for a three-level inverter reliant on two level inverter. The three-level break vector chart is isolated into six two-level break vector graphs. A two-stage to three-stage modify is expected to ascertain the point to move of source of a virtual two-level inverter. Consequent to the go of cause and 600 facilitate change; on-times are resolute utilizing two-level conditions. Notwithstanding for three levels, this method requires a bigger number of calculations than the expected procedure. Be that as it may, this practice can't be legitimately connected to a n-level inverter.

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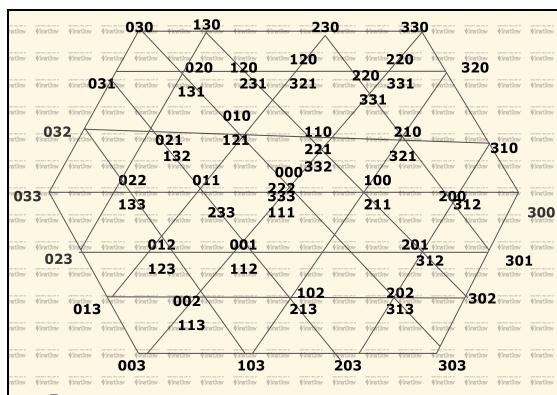
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## II. DIODE CLAMPED MULTILEVEL INVERTER:

The amount of basic switches in each topology is proportional. Assessment with various sorts, diode clamped inverters need less number of capacitors yet need extra catching diodes. Subsequently the diode secured stunned structure is better for high and medium electrical energy drives which are viably connected with the utility drive. The diode clamped multilevel inverter normally contains  $(m-1)$  capacitors on the dc transport in which  $m$  is indisputably the capacity of positive, negative and zero levels in the yield power. Figure1 shows a three phase half-interface four level diode supported inverter. The solicitation for numbering of the switches for stage  $x$  is  $ta_1$ ,  $ta_2$ ,  $ta_3$ , and  $ta_1''$ ,  $ta_2''$ ,  $ta_3''$  and correspondingly for other two phases. The dc transfer includes four capacitors  $c_1$ ,  $c_2$ , and  $c_3$  go about as electrical energy divider. For a dc transport electrical energy  $V_{dc}$ , the electrical energy over each capacitor is  $V_{dc}/3$  and current weight on each (switch) contraption is confined to  $V_{dc}/3$  through supporting diode. The midpoint of the three capacitors "n" can be described as the unbiased point. Table 1 shows the yield electrical energy levels and the looking at switch states for one time of the selected four levels DCMLI. The switches are planned into 4 sets  $(ta_1, ta_1'')$ ,  $(ta_2, ta_2'')$ , and  $(ta_3, ta_3'')$ . If one switch of the pair is turned on, the comparing switch of a comparative pair must be off. Three switches are actuated whenever of time to pick the required level in the four levels DCMLI.

**Table1:** Sector and switching state mapping

Sector	Phase A	Phase B	Phase C
P1 Published By: <i>Blue Eyes Intelligence Engineering &amp; Sciences Publication</i>	$T_a$	$T_b$	$T_c$
P2	$-T_b$	$-T_c$	$-T_a$
P3	$T_c$	$T_a$	$T_b$
P4	$-T_a$	$-T_b$	$-T_c$
P5	$T_b$	$T_c$	$T_a$
P6	$-T_c$	$-T_a$	$-T_b$



**Fig 1: Space vector diagram for four level converters**

## On time calculations of space vector four level converters:

$$V^s T_r = V_n T_a + V_m T_b \quad (1)$$

Volte second component  $V^s$   $V_n$  and  $V_m$  Of along  $\pi - \alpha$  axis

$$V_\pi^s T_r = T_a + T_b \quad (2)$$

$$V_\alpha^s T_r = ZT_b \quad (3)$$

$$T_r = T_a + T_b + T_c \quad (4)$$

*Solving eq (2)and (4)on time calculations*

$$T_a = T_r \left[ V_\pi^s - \left[ \frac{V_\pi^s T_r}{z_Z} \right] \right] \quad (5)$$

$$T_B = T_R [V_\alpha^S/z] \quad (6)$$

$$T_C = T_r - T_a + T_b \quad (7)$$

## Vector angle

$$S_i = \text{int} \left[ \frac{\theta}{60} \right] + 1 \quad (8)$$

$$S_i = \text{int} \left[ \frac{\theta}{60} \right] \quad (9)$$

### *$\pi$ and $\alpha$ Phase voltages*

$$V_{\pi,ref} = 1/3 \frac{(V_{A,REF} - V_{B,REF} + V_{V,REF})}{2} \quad (10)$$

$$V_{\alpha,REF} = \frac{1}{\sqrt{3}}(V_{b,ref} - V_{c,ref}) \quad (11)$$

### Triangular $\Delta_\eta$ and $\Delta_k$ eqn

$$\Delta_n = P_1^2 + 2P_2 \quad (12)$$

$$\Delta_k = P_1^2 + 2P_2 + 1 \quad (13)$$

## **II COMPARISON OF A CARRIER BASED PULSE WIDTH MODULATION AND SPACE VECTOR PULSE WIDTH MODULATION:**

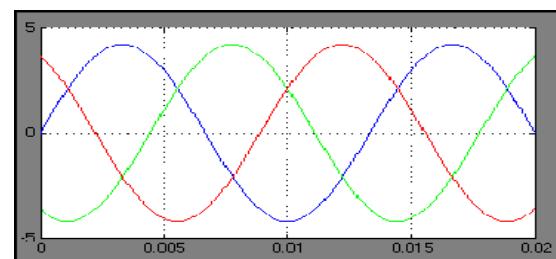
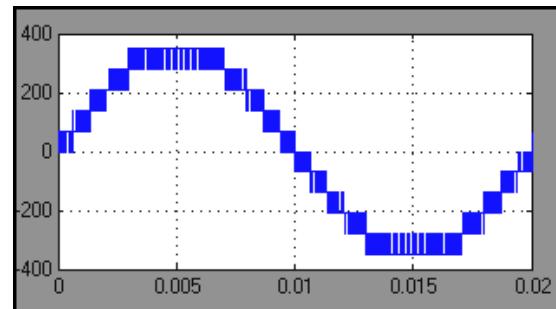
Carrier based pulse width modulation is defined as a one offset common mode off set signal is added to a sinusoidal signal to obtain the reference wave form then compared to the carrier waveform. This offset signal is to reduce the harmonic distortion then higher modulation signal. Then the diode clamped multilevel inverters have added off set signal then the harmonic distortion is reduced then incurrence power quality. Carrier based pulse width modulation frequency is 50 Hz and THD is 32.5%. And break vector plus width modulation is defined has a single vector derived from the three phase reference signal. SVPWM is to reduce the THD and less computation period. Simulation result for basic frequency 50 Hz and THD is 41.98%. Four level diode clamped multilevel inverter is then frequency is increasing then total harmonic distortion is decreasing.

below updating result is observed basic frequency is increasing up to 50hz to 120hz then THD is lowly decreasing up to 41.98% to 87.14%.also five level diode clamped multilevel inverter is currently THD result is change in the special basic frequency. Diode clamped multilevel inverter are two pair switches on at a time.THD is increasing then increasing and weighted in width of basic wave. a four level diode clamped multilevel inverter for basic frequency is changed it also changed in THD results. Number of level increases then harmonic is reduced. Break vector is very easiest method then calculate the nearest vector, dual time calculation and function cycle calculation. Mostly used in presentation discontinuous pulse width modulation. This technique is low yield harmonic distraction and switching frequency is increased for three level converters. Lower weighted THD for four level converters. The staggered inverter is a good number appropriate for the application. This requests the nature of the air conditioner supply waveforms. This work introduces a SVPWM control plot, which relates full diode clamped staggered inverters. A three stage four-level a three stage RL heap of 16.5 ohm and 10 mH is connected over the yield of inverter. The exchange grouping for three stage four-level inverter. Load fault of a three phase current will be occurred in output segments. Then the on time and off time period 2sec then the output current. in this paper, we proposed a basic calculation to play out the SVPWM for diode clamped four level inverter. The on-time count depends on two levels SVPWM calculation that is basic and the on-time figuring situation doesn't change with the situation of position vector like the regular calculation. In the space vector graph of a m-level inverter [7], the triangle where the position vector is found is identified as whole number  $\Delta n$ . Any exchanging grouping can be executed with regard to triangle  $\Delta n$ , prompting an effectiveness and flexibility of advancing the exchange deal. In our proposed control method, there are just four dynamic exchanging states for first triangle rather than 10 and same concerning others. This plan can be operate for any n- level inverter with no significant increment in calculations.

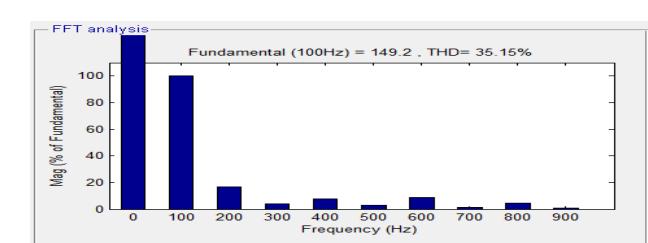
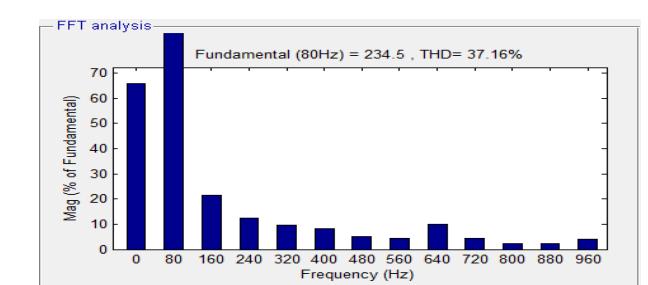
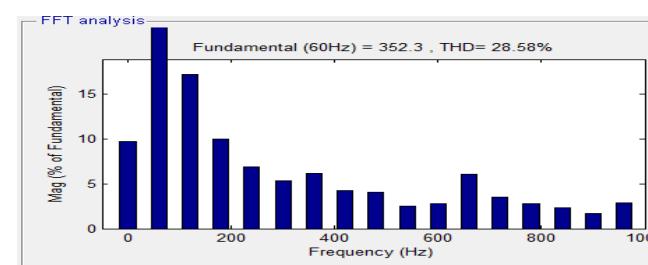
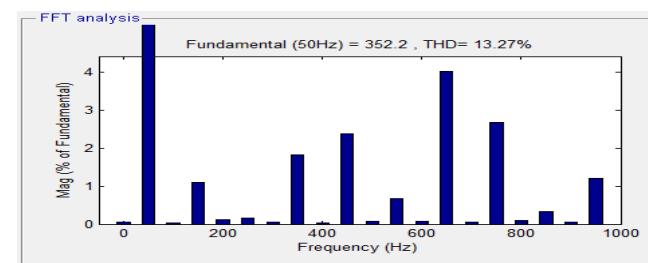
### III MODELING & SIMULATION RESULT FOR DIODE CLAMPED MULTILEVEL INVERTER:

the staggered inverter is most appropriate for the application which requests the nature of the air conditioner supply waveforms. This work exhibits a SVPWM control plot, which relates full diode braced staggered inverters. A three stage RL heap of 16.5 ohm and 10 MHz is related over the yield of inverter. The exchange groupings for three stage four-level inverter are given in table 2. then the switching states of diode clamped multilevel inverter any three switches can on in at a time. That THD figuring's are not confined to sinusoidal flag however can be connected to any ceaseless flag, for example, square wave or triangle signals. in addition remember that there are unusual definition for the THD factor and how it is determined. Some depict the demonstrator of with information of both principal recurrences just as sounds. Different definitions do likewise add commotion to the computations.

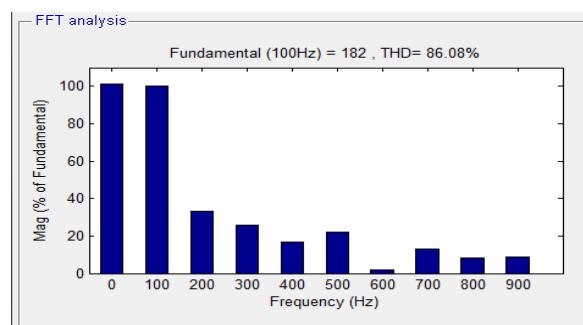
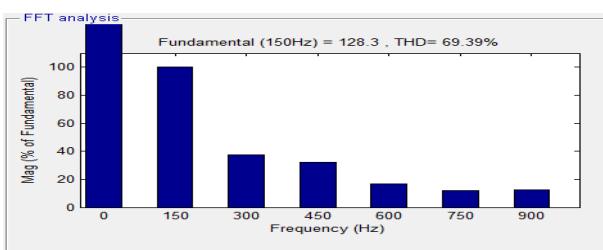
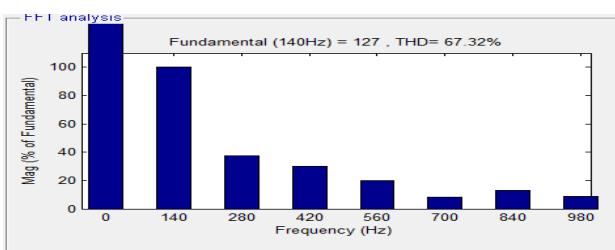
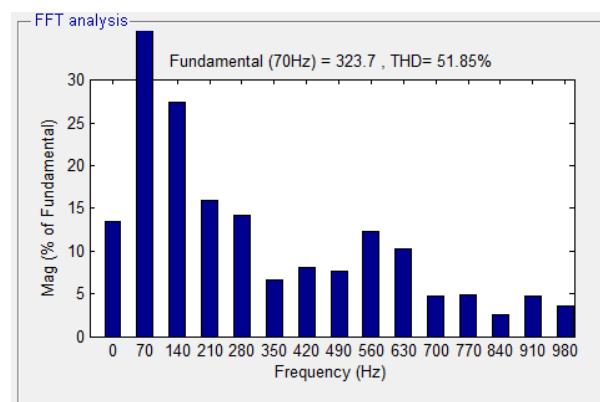
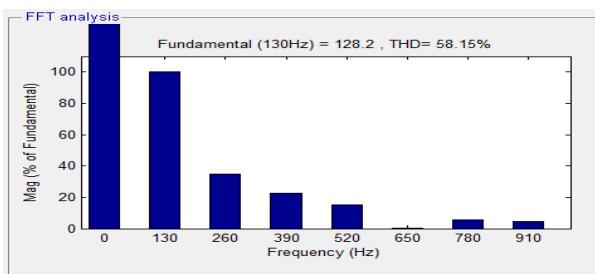
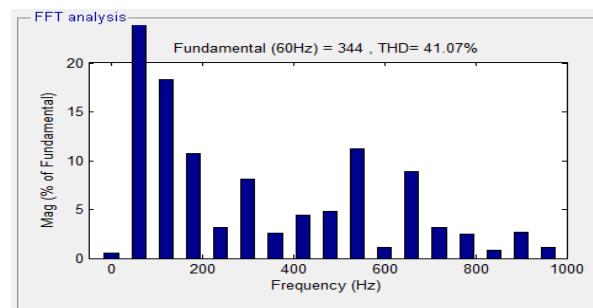
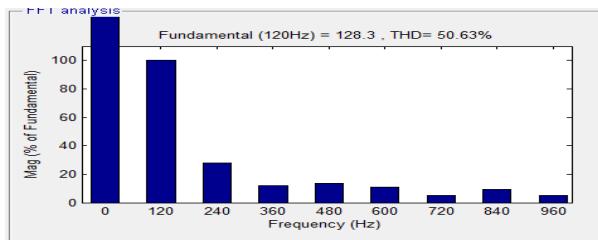
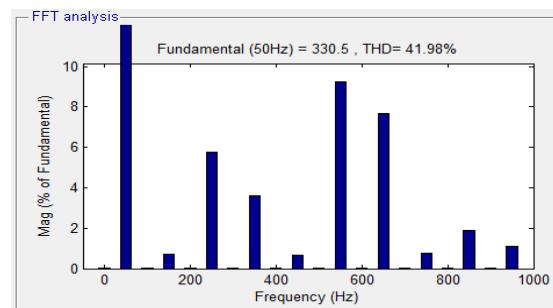
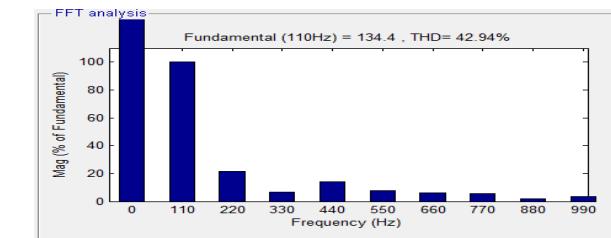
Single Leg Five Level Output For Diode Clamped Multilevel Inverter:



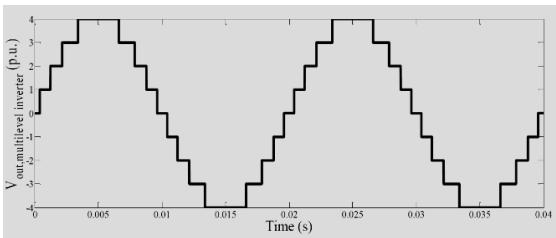
line to ground fault in three phase diode clamped multilevel inverter:



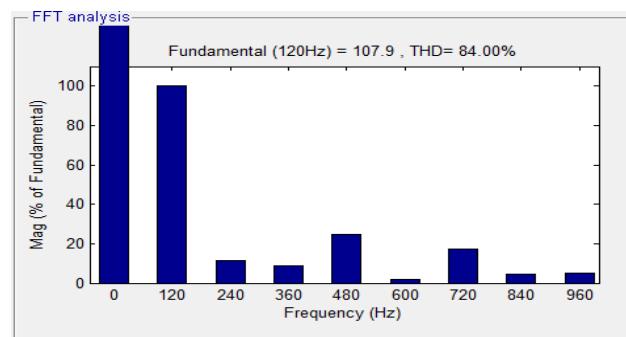
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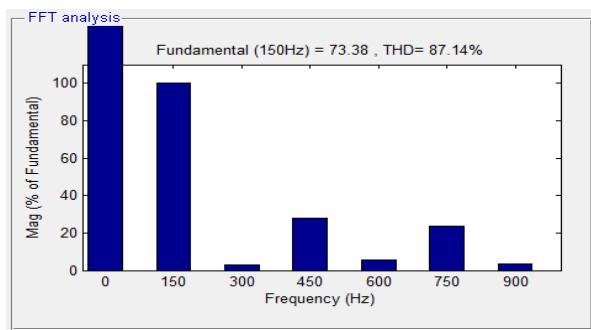
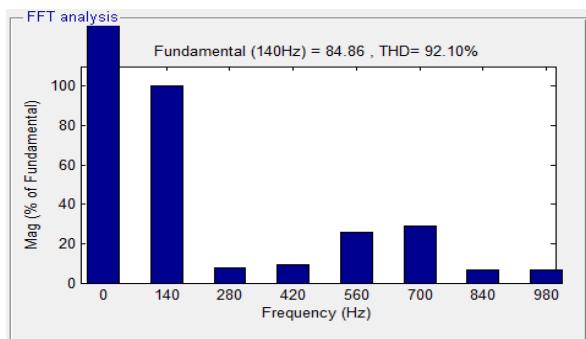


Single Leg four Level output For diode clamped multilevel inverter:



phase to ground fault in three phase diode clamped multilevel inverter:





T1	T2	T3	T4	T5	T6	Output voltage
1	1	1	0	0	0	$V_{dc}$
0	1	1	1	0	0	$2V_{dc}/3$
0	0	1	1	1	0	$V_{dc}/3$
0	0	0	1	1	1	0

Table2: switching states for four level diode clamped multilevel inverter

### III. CONCLUSION

In this Paper simulation results for three phases four level diode clamped inverter and five level diode clamped multilevel inverters are obtained through MATLAB/SIMULINK. From the simulation result for better perform the carrier based pulse width modulation technique. It can be the four level diode clamped multilevel inverter based on space vector pulse width modulation technique gives enhanced fundamental output with better quality i.e. lesser THD compared than others. Major cause of impulsive failure of motor bearings and winding. Multilevel inverters reduce dv/dt & leakage current which are responsible for Precipitate failure of bearing and winding. As the level of Inverter goes on increasing it has been observed that the Total Harmonic Distortion decreases. This topology can be applied to medium voltage & low voltage drives to increase the life of bearing of motor and improves the reliability of motor.

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