Flow Simulation over a Bulbous Heat Shield of a Typical Launch Vehicle

Manoj R, Ranjith Kumar A, Gopalsamy Murugesan, P. Jeyajothiraj

Abstract: Numerical Simulation of flow field over a sharp and blunt nose cone bulbous heat shield are carried out. Software used for the simulation is ANSYS 19.2 student version. The Simulations are carried out in the Mach no. range 0.8 to 1.2 (transonic regime). Simulation results are analyzed in detail. Besides, Shock Strength on the heat shield for all the simulation results are obtained. Based on the studies, bulbous heat shield which gives least shock strength is recommended for the payload fairing configuration.

Keywords : Sharp and blunt nose cone, Bulbous heat shield, Numerical Simulation of flow field, Payload fairing configuration.

I. INTRODUCTION

The payload fairing in any launch vehicle is needed to protect the satellite from aerodynamic loading, aerodynamic heating and other environmental conditions during the ascent phase of the flight and to provide an aerodynamic forward surface Bulbous Heat Shields are essential for accommodating larger payloads on launch vehicle configurations. The flow field visualization over a bulbous payload shroud at transonic Mach number range is very useful to decide the geometrical configuration for minimum aeroacoustical loading, minimum buffeting load and minimum aerodynamic drag requirement. The terminal shock wave of sufficient strength intersecting with the boundary layer can cause flow separation and the flow field may become unstable as observed in the high speed, it is desirable to determine the location of the terminal shock as a function of transonic Mach numbers. The strength of terminal shock and the mechanism of its interaction are related to the specific configuration of the heat shield of satellite launch vehicle.

The features of the transonic flow field can be delineated through the theoretical and experimental investigations. It is characterized by a terminal shock, supersonic pocket on the cylindrical region of the heat shield, shock wave-turbulent boundary layer interaction, and a separated bubble that may be caused by the shock wave-turbulent boundary layer on the cylindrical section of the heat shield. In the boat-tail region, a local separation results due to sharp discontinuity in the longitudinal direction of the payload shroud. The regions of flow separation impose additional complexity to aerodynamic and structural design aspects. The pressure fluctuations that originated at the location of the normal shock wave within the regions of separation can cause buffeting problem. The occurrence of buffeting of vehicle during transonic range depends primarily on the geometrical parameters of the payload shroud. The complex flow field at the transonic speeds is also observed during the wind-tunnel testing of the bulbous heat shield. The present study employs a computational fluid dynamics approach to analysis a complex fluid dynamics problem of the launch vehicle in the transonic Mach number range. The time-dependent, compressible, turbulent Reynolds-averaged Navier–Stokes equations are solved using a finite volume discretization in conjunction with a three-stage Runge–Kutta time-stepping scheme.

Charles et.al [1] investigate the Steady and fluctuating pressures measured along the top center lines of three space-vehicle models with hammerhead-shaped profiles within the Mach number range from 0.60 to 1.17. The results of the investigation showed that flow separation due to the hammerhead configuration can expose large areas of the vehicle to significant pressure fluctuations. R.C. Mehta et.al [2] analyzed the unsteady, turbulent, compressible, axisymmetric flow. Reynolds-averaged Navier–Stokes equations are solved for the flow past a bulbous payload shroud for a freestream Mach number of 0.95. A time-dependent numerical simulation is carried out using a finite-volume discretization technique. Senthikumar et.al [3] studied the shock movements on the heat shield. The extents of separation zones behind the boat tail region are also estimated. S.Parameshwari et.al [4] investigated the transonic flow field over launch vehicles with strap on boosters. They found that the location of strap-on booster are critical due to presence of aerodynamic phenomena, such as shock-boundary layer interaction, subsequent flow separation.

Pranav Mahamuni et.al [5] analyzed the shock waves formed in the transonic region of flow, which makes the fairing the most unstable in this phase. Studied the methodology for reducing the unsteady pressure levels and hence also the aeroacoustical loading in the transonic region...
i.e. Mach number 0.7 to 1.2. From their study it is found that the separation area as well as the shock strength must be reduced. K. Manokaran et.al [6] simulated the flow over various payload fairing configuration in transonic Mach numbers. This types of Hammerhead/Bulbous Payload Fairing (PLF) creates unsteady aerodynamic effects especially in the transonic Mach number regime. R.C. Mehta et.al [7] computed the aerodynamic coefficients for various bulbous heat shield of a typical satellite launch vehicle at supersonic speeds. Numerical simulations are carried out by solving time-dependent, three-dimensional, compressible Euler equations in conjunction with a finite volume scheme at freestream Mach number 1.2 and 1.8. M Prasath et.al [8] fluctuating pressure measurements out over heat shield, boat tail and on core cylinder region of a generic launch vehicle having bulbous heat shield and strap-on configuration. Hence the understanding of flow field with separation and reattachment is of immense importance in design and control aspects of launch vehicles.

II. METHODOLOGY & RESULTS
A. Launch Vehicle Nose Cone Configuration for PLF.
General launch vehicle nose cone geometrical configuration illustrated in figure 1.

Fig.1 General Nose cone geometrical configuration.

B. Types of PLF Configurations
A very common nose-cone shape is a simple cone. This shape is often chosen for its ease of manufacture. More optimal, streamlined shapes (described below) are often much more difficult to create. The sides of a conic profile are straight lines.

Fig.2 Sharp nose cone PLF

A conical nose is often blunted by capping it with a segment of a sphere. The tangency condition is implemented where the sphere meets the cone.

C. Geometry Considerations
The Geometry taken are a simple sharp nose cone and blunt nose cone. The dimensions of the geometry configuration as follows:
- Sharp nose cone dimensions:
  Total length = 150mm.
  Nose cone angle = 29.64°.
  Cylinder diameter = 24mm.
  Cylinder length = 58.63mm.
  Boat tail angle = 142.74°.
- Blunt nose cone dimensions:
  Total length = 150mm.
  Nose cone angle = 29.36°.
  Cylinder diameter = 21.41mm.
  Cylinder length = 53.76mm.
  Boat tail angle = 127.94°.

D. Modelling of the geometries
Two different geometries are modelled, as sharp nose cone and blunt nose cone.

Fig.3: Blunt nose cone PLF

The idea of this research work is to understand the effects of shock at different locations in a different PLF configurations and to identify the variation trends of difference parameters like pressure distribution over the heat shield fairing, Shock location etc. The objective of this series of computational analysis is to obtain the flow fields that are generated due to the shock taking place in the heat shield for study the effects of shock wave movements on the nose cone body, obtain the flow parameters from the simulations and derive the shock strength.

Fig.4 General Model of the sharp nose cone
III. NUMERICAL SIMULATIONS

The flow simulations require the following steps:
1. Modelling of the geometries.
2. Meshing the geometries and grid/mesh generation in the computational domain.
3. Solving the unsteady 3-Dimensional Navier-Stokes equations using finite volume method to obtain the steady state converged results.

Step 3 further requires:
   a. Turbulence modelling and
   b. Boundary condition.

Spalart- Almarar turbulence model is used in these simulations. Velocity inlet, pressure outlet and wall boundary conditions are utilized to obtain steady state solution.

IV. RESULTS AND DISCUSSIONS

Pressure distribution over blunt nose cone along the longitudinal axis for different Mach numbers are given in Figure 6 to 12.

Pressure distribution at 0.9 Mach shown in Figure 9. Nose cone center stagnation pressure 49 kPa, The pressure decrease continuously in the spherical nose cap and reaches a value of 10 kPa at the curvature discontinuity location between spherical nose cap and nose cone. Pressure continues to decrease and reaches a minimum of about -25 kPa with a drastic drop at the nose cone cylinder junction due to expansion at this location. The pressure tries to recover to free stream value and reaches -7 kPa at the end of the cylindrical section. Since flow encounters another expansion corner at the cylinder-boat tail function and pressure drops to slightly and recover back to free stream in the cylindrical portion after the boat tail.
Pressure distribution at 1.0 Mach shown in Figure 10. Nose cone center stagnation pressure 62 kPa. The pressure decrease continuously in the spherical nose cap and reaches a value of 15 kPa at the curvature discontinuity location between spherical nose cap and nose cone. Pressure continues to decrease and reaches a minimum of about – 30 kPa with a drastic drop at the nose cone cylinder junction due to expansion at this location. The pressure tries to recover to free stream value and reaches -5 kPa at the end of the cylindrical section. Since flow encounter another expansion corner at the cylinder-boat tail function and pressure drops to slightly and recover back to free stream in the cylindrical portion after the boat tail.

Pressure distribution over the sharp nose cone at 0.9 Mach shown in Figure 11. Nose cone center stagnation pressure 58 kPa, the pressure decrease continuously up to the junction of nose cone and cylinder and absent of effect of the spherical nose cap clearly shown in Figure 11. Pressure continues to decrease and reaches a minimum of about – 45 kPa with a drastic drop at the nose cone cylinder junction due to expansion at this location. The pressure tries to recover to free stream value and reaches -10 kPa at the end of the cylindrical section. Since flow encounter another expansion corner at the cylinder-boat tail function and pressure drops to slightly and recover back to free stream in the cylindrical portion after the boat tail.

Pressure distribution over the sharp nose cone at 1.0 Mach shown in Figure 12. In the Sharp nose cone normal shock stands close (Almost attached) to sharp leading edge of the nose. Nose cone center stagnation pressure 100 kPa, Pressure loss to the higher in blunt nose cone compare to the sharp nose cone. Pressure continues to decrease and reaches a minimum of about – 80 kPa with a drastic drop at the nose cone cylinder junction due to expansion at this location. The pressure tries to recover to free stream value and reaches -25 kPa at the end of the cylindrical section. Since flow encounter another expansion corner at the cylinder-boat tail function and pressure drops to slightly and recover back to free stream in the cylindrical portion after the boat tail.

V. CONCLUSION

Detail study has been carried out for bulbous heat shield with blunt and sharp nose cones. Based on comparing the pressure distributions, the following conclusions are derived

1. Stagnation pressure of sharp nose cone and blunt nose cone are 100 kPa and 62 kPa at 1.0 Mach number. It clearly state the pressure loses in the blunt nose cone is higher than the sharp nose cone due to bow shock wave forms in front of the spherical cone.
2. Due to high stagnation pressure in blunt nose cone, the lesser pressure drop in the nose cone and cylinder junction compare to the sharp nose cone.
3. Blunt nose cone is preferable not only from the heat transfer point of view but also from the structural load aspects also.

REFERENCES


AUTHORS PROFILE

R Monoj, UG Scholar, B.Tech. Aerospace Engineering, Karunya Institute of Technology and Sciences, Coimbatore.


Gopalsamy Murugesan, Research Scholar, Department of Aerospace Engineering, Karunya Institute of Technology and Sciences, Coimbatore.

Dr. P. Jeyajothiraj, Professor, Department of Aerospace Engineering, Karunya Institute of Technology and Sciences, Coimbatore. Former Scientist ‘G’ from Indian Space Research Organization (ISRO). Specialization: Aerodynamics, Gas Dynamics, Experimental Aerodynamics, Acoustics and Aeroacoustics.