

# Optimization of SPEC sensing with estimated information for CRN

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**Abstract:** The cognitive radio networks Corresponding amount of traffic rapidly expanding on a sensing and interference spectrum management on a finite number of possibly unoccupied channel over available whitespace on radio spectrum. Database estimated information by real time sensing with geolocation to enhance resolution accurately occupancy over a wide frequency bands occupied by primary user. Proposed develop cooperative sensing algorithm sequential optimal even low signal noise ratio region. Estimated information ensuring disclosure accurate experimental results on simulated proposed method improves the sensing sensitivity enhanced to previous work with low complexity and limited amount interference.

## I. INTRODUCTION

Research focused on the secondary users establishing single link between available resources identify the challenges implementing a Wi-Fi like cognitive radio network consisting of access points associated with unused members. Access points associated with multiple secondary clients [1]. To measure wi-fi networks by sniffers which is dedicated hardware components measuring the MAC information via wire side monitoring by passive methods. The monitoring process involves numerous applications faultdiagnosis to resource management and communication forensics. Build traffic monitoring a nontrivial framework which important for resource cognitive is difficult to manage but easy to programmable, and interference is to high with primary user resources alternative monitor for wi-fispectrum When Pus start transmission on channels sniffers problems to identifies traffic monitoring but multiple secondary resource share spectrum MAC traffic patterns observed dynamically by sniffershaving monitoring strategies[8]. In cognitive radio initially identifying spectrum holes and used by Sus. Transmissions of licenced users reliably quickly with robustness. When found allocated resource is vacant ie white space that can be efficiently with guarantied inference to licencedresource holders, this involves accessing quickly and probably weak users resources. Utilizing estimated of non-parametric density use of monitoring frame work spec sensors to proposed, Second number of active users by behaviour analysis [6]. finally monitoring analysis by quality a) Construct non parametric model for density estimation mechanism secondary user channel activity.

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That is, support dynamic and complex access patterns b) Developing algorithms for channel switching and assignment of integer programming by optimizing two different level c) statistical model for monitoring frame work for accurate estimation by simulation. Process having two access methods sensing and data communication phases.

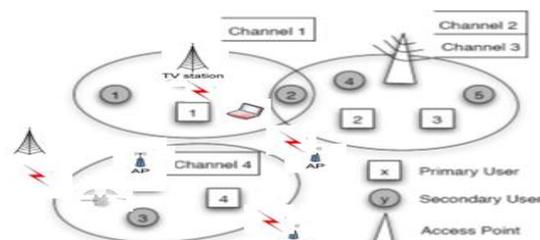


Fig 1a Monitoring system and architecture

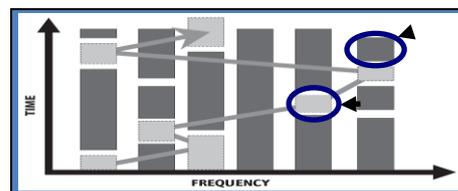


Fig 1 b Time slots for cognitive networks

The secondary users find white space in sensing phase in particular time and geo location and another secondary transmit data on detected white space spectrum hole.[3]. Previous all sensing methods uses energy detection, cyclostationary and matched filters due to less computation energy detection widely used. But scenarios like noise and its effectness identifying cloud be effected, another situation low SNR differentiating the primary signal from the interference and noise get good sensing in cyclostationary. where noise rejection property fails to find energy detector fails to find spectrum unused resources. Reference gives the basic methods to detect the presence of cyclostationarity and apply this methods in the spectrum sensing. Work organized Initially proposed work started with monitoring archecture then related work, and start with Monitoring model and proposed analysis, algorithms and process approached, simulation and results, conclusions and some snapshots of graphs of proposed methods.

II. RELATED WORK

The spectrum sensing and its categories and described several spectrum sensing techniques applied to detect available white space the awareness, reliability and adaptability nature of CR networks make it more precious to be deployed successfully in near future. Simulate Sus in network far from Pus in cognitive radios transmitter is randomly distributed work regarding the efficient identification of available spectrum space[7].The investigated the operation of WSRNs or TVWS networks along a number of field trials. The results from these trials have shown that indeed WSRNscanprovide a information regarding the harmful interference where the tvband sufficient throughput via 4-8Mbps. In rural using tv channel of low frequency bandwidth, to access through measurements and accuracy challenges with available estimated information of geolocation database.[8].the traditional network monitoring Yeo etal. Used spec sniffers identify the malicious and anomalies directness in usages wireless LAN .author cheng et al discussedJigsaw, which is a large-scale passive monitoring traffic for cross-layer in large wi-fi network[4][5].related information identifies to access channel slots to maximum utilization of information. While mesh network huge coverage problem formulated with designed algorithm's to solve by Shin et al..For spectrum sensing, primarily three signal processing techniques are proposed in literature: Matched filter n-Matched filtering is optimal but requires detailed knowledge of primary signalling. When no such knowledge is available an Energy.To provide optimal solution with energy detection. Where the cooperative spec sensing methods mixed with assumptions decision detect spectrum hole made certain observations from nodes.

III. MONITORING MODEL AND PROPOSED ANALYSIS

To sensing the available unused spectrum in radio network simple diagram fig1a and fig 1b where primary users and secondary users along with spec monitor Tv towers and microphones to analyse the traffic network justifies client want to access initially observes the topography and form a wifi network [7]which include operational sniffers which communicate through sending the information regarding location information sniffer center each segment small regions areas where monitoring each sniffer with antenna and equipped sensing components which allow sense are capture over multiple channel one time durations. Here pairing of clients in the monitoring area inbound and outbound traffic from secondary monitoring area, dedicated sniffers continuously sense the channels collecting information statistics. all captured information. From sniffers are connected to a sniffer center. for centralized decision making sensing slot assigned to Each inspection sniffer is assigned multiplechannels to scan and sensing.Consider fig2 network gives bunch communicating without loss of generality over certain licensed bands. Here symmetry of data transfer from primary user1 to and another In fusion center with error free secondary user including find any spectrum hole, when

information collected at secondary user uses the hole to transmit their data in the transmission phase.

$$x_i(t) = \gamma_i s(t) + n_i(t), \quad i = 1, 2, \dots, N,$$

the i-th user's received discrete in the sensing phase,  $\gamma_i$  denotes the channel gain from the PU to the i-th SU and  $n_i(t)$  with zero mean on received noise. Primary user signal and noise are not limited to distribution. Fusion centre link them sequentially to form a new time series

$$y(t) = [x_1(t), x_2(t), \dots, x_N(t)]$$

presence of cyclostationary which will be used for the final detection of the. *First-order Periodicity*

Define  $x(t) = s(t) + n(t)$

where  $n(t)$  is a zero-mean Gaussian noise and  $s(t)$  is a deterministic complex sinusoidal signal determining the parameter  $A, \theta$  and in the signal  $s(t)$  are constant the mean value of the signal expressed as

$$s(t) = A e^{j(2\pi f_0 t + \theta)}$$

$$M_x(t) = E\{x(t)\} = A e^{j(2\pi f_0 t + \theta)}$$

Clearly,  $M_x(t)$  is a function of time  $t$ . Thus the value  $A$  cannot be obtained from direct average of  $x(t)$ . And considering second order finally spectrum sensing Consider the fused time series  $y(t)$ , which is a zeroing non-stationary complex signal. The correlation function of  $y(t)$  is defined as

$$R_y(t; \tau) = E\{y(t)y^*(t - \tau)\}$$

Noting that  $E\{y(t)y^*(t)\}$  is a special case for  $R_y(t; \tau)$  when  $\tau = 0$ . If  $R_y(t; \tau)$  is a periodical function of time  $t$  with period  $T_0$ , then it can be decomposed into the sum of a set of complex exponentials

$$R_y(t; \tau) = \sum_{m=-\infty}^{\infty} R_y^\alpha(\tau) e^{j2\pi \frac{m}{T_0} t} = \sum_{m=-\infty}^{\infty} R_y^\alpha(\tau) e^{j2\pi \alpha t}$$

where  $\alpha = \frac{m}{T_0}$  and  $R_y^\alpha(\tau)$  is the Fourier co-efficiencies also considering the energy detector of the Primary nodes below numerals

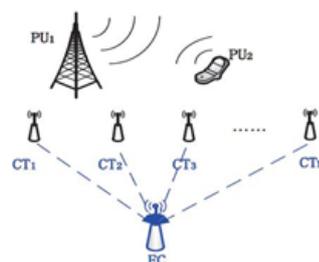


Fig 2 fusion center

II ALGORITHMS AND METHODS PROPOSED

Time required for sensing increased due to probability of detection via reducing probability of false alarm also it reduces available transmission time, if most of the time idle found in primary user then use higher probability will be active in detection period, a optimizing for nonlinear algorithm it will minimize the time Method used first monitoring given that the Cognitive radio in state k,



## Optimization of SPEC sensing with estimated information for CRN

Minimum monitoring time executed every detected cycle, then search time executed when idle but shows busy by probability  $\Pr(i)(H_0) * P(H_1|H_0)$ , to achieve primary user detection probability condition with true negative ( $\Pr(H_1|H_1)$ ) of primary user must be greater than or equal to given detection probability ( $\hat{P}_d$ ). Time should be minimum detection period with Monitoring when low SNR also able to detect primary user considering non-linear formulation try to minimize search time along with interference null with more probability for available channel in search time then cognitive radio node detect idle channel with probability at least equal to the threshold time in Search optimization

$H_0, y(n) = w(n), H_1, y(n) = x(n) + w(n)$

Where  $W(n)$  is noise samples  $\sim N(0, \sigma_w^2)$ ,

$X(n)$  is signal samples

$n = 1, 2, \dots, N$

Test Statistics  $T = \sum_{n=1}^N [Y(n)]^2$

$n = 1, 2, \dots, N$

Test Statistics  $T = \sum_{n=1}^N [Y(n)]^2$

$$H_e = \begin{cases} 0, & T < \lambda \\ 1, & T > \lambda \end{cases}$$

where  $\lambda$  is the decision threshold

Distribution of T (CLT)  $T \sim N(N\sigma_w^2, 2N\sigma_w^4)$  under  $H_0$

Use Gaussian distribution

$$P_{FA} = Q\left(\frac{\lambda - N\sigma_w^2}{\sqrt{2N\sigma_w^4}}\right) P_D = Q\left(\frac{\lambda - N(\sigma_s^2 + \sigma_w^2)}{\sqrt{2N(\sigma_s^2 + \sigma_w^2)^2}}\right)$$

Decision Threshold

$$\lambda = \sigma_w^2 (Q^{-1}(P_{FA})\sqrt{2N} + N)$$

Constant False Alarm Rate (CFAR)

In order to decide threshold  $\lambda$ , choose  $P_{FA}$  want to achieve.

Parameters for implementation

Average noise level = -159 dBm/Hz = -91.21 dBm over 6MHz

(Spectrum Sensor : ThinkRF WSA4000)

$\sigma_w^2 = -91.21$  dBm,  $P_{FA} = 0.1$ ,  $N = 10$ ,

Decision Threshold  $\lambda = -79.03$  dBm

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The energy detection and cyclostationary flowcharts shown. A sensing technique, Correlation distance based spectrum sensing, was developed and used to measure the occupancy of channels. A Utility function is being developed to rank and select the best channels. This utility (usefulness) function is defined by

$$U_{xy} = [w_x (U_x)^r + w_y (U_y)^r]^{1/r}$$

where,  $w_x$  and  $w_y$  are weights,  $U_x$  and  $U_y$  are the individual utility values for SNR and spectrum occupancy, and  $r = \frac{s-1}{s}$ , where  $s$  is the elasticity of substitution. [7].

Flow chart of detecting sensing for primary user space by random sensing and all channel sensing gives complete access scenario of the related spectrum sensing efficient approaches given

Optimized method consider find available spectrum hole from Pus. Given calculated algorithm Analytical Hierarchical process view for estimated by white space database

- 1 INPUT White database types with white space channels
- 2 G: OUTPUT making vector for whitespace hole for global priority
- 3 > compare with AHP having enough white space spectrum
- 4 If  $C \geq 2$  then, find whitespace of same type u
5. Matrix Aun :wn :from weighted vector of Generate weighted vector
6. k do criterion for Every event
7. Pairwise Comparison matrix Bk with by build a performance matrix
8. End for
9. The judgement matrix M constructed
- 10 computing g: by vector of global priority values
- 11 Return when Rank g in decreasing order
12. End for
13. Else //only one white space spectrum
14. WSD allocates it based on FCFS so long it meets the requirements:
15. End if
16. Procedure End.

Sensing channel Optimized search algorithm

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A. IF Node Start/channel busy, Then
WHILE (channel Found =False), DO
[k,TH[K],N[K], assign optimize(channel
sequence[M],SNR[M]Po[M],Pd[M])
Channel found assign Find channel(K,Th K, N[K])
IF Channel found THEN
Start using the channel
BREAK
Else
Channel assignchseq – First K value
SNR assign SNR- First K value
Po assign PO -First K value
Pd assign Pd - First K value
END IF
END WHILE
END IF
// find channel sense the K channels sequential until finds
channel
FUNCTION Find channel (k,Th[k],N[k])
i assign 1
Channel available assign False
WHILE i less than or equal to K
And channel available = false do channel available assign
DO ENERGY DETECTION (ch I th t, Nt),
If Chavailable = True then
Return channel Available
End if
i=i+1, end while
Return channel available
If sense the channel find Low/high SNR then
If channel available = Low SNR then assign DO
Cyclostationary auto correlation detection
Return channel available.
End if
    
```

The above two sets of algorithms initially detection of the white space by WSD. Which concludes experimental accurate availability channel sensed with probability with estimated radio resources, then optimized method energy detection and cyclostationary with autocorrelation method which ensures the accurate probability of availability of channel what is justified. The waveform with pure signal and noise simulated scenario demonstrated on shown annexure figure the calculation of  $M_x^\alpha$  with different  $\alpha$ . Shown in fig 2, where real part  $M_x^\alpha$  nonzero frequency point is approximating to zero, from cloud obtain the first odder cyclostationary signal while the second-order cyclostationary situation Here set  $x(t) = A(t) \cos(2\pi f_0 t) + n(t)$ . diagram noise and signal original.  $M_x^\alpha$  of  $x(t)$  is also calculated, regulation in this figure due to the reason that  $E\{x(t)\} = E\{A(t)\} \cos(2\pi f_0 t) + 0 = 0$  Thus find  $M_y^\alpha$  with different  $\alpha$ . in third diagram performance algorithm proposed find cyclic frequency at nonzero point off  $M_y^\alpha$  fix  $s(t)$  to be a zero mean time series with  $m = 1, 2, \dots, T$  duration  $T$ , and  $y(t)$ . Thus the cyclic frequency is  $\frac{m}{T}, m = 1, 2, \dots$ . when  $\alpha$  is the integer multiplies of the cyclic frequency, the absolute value of  $R_y^\alpha$  is much larger than the other case is shown in secondary user networks generally,  $T$  could be set previously by the controller. To calculate presence cyclostationary through the absolute value of  $R_y^\alpha$  where  $\alpha = \frac{m}{T}$ ,

V. RESULTS AND DISCUSSION

The traditional energy detector along with Gaussian distribution considered for the simulation sensed results here static data with modified cooperative so in negative SNRs region energy detector detection results of cyclostationary Here set  $x(t) = 6 \cos(2\pi f_0 t) + n(t)$  the waveform based on pure signal with noise on cosine waveform calculation of  $M_x^\alpha$  with different  $\alpha$ . all the obtained values discussed in above  $R_y^\alpha$  where  $\alpha = \frac{m}{T}$ ,  $m = 1, 2, \dots, T$ . Finally, the performance of the proposed detection algorithm the results an snapshots give achieved is figures shows the experimental analysis where y axis obtained amplitudes and cyclic frequencies and the signal and also signal plus noise where time and another obtained spectrum usage real and imaginary part to analyse the diagram exact amount of slot used by the primary user and on time some slot can be used accurately when even noise will be there by secondary users. Using  $\alpha = \frac{m}{T}$ ,  $m = 1, 2, \dots, T$  can obtain more values availability of slots primary users accurately finally acquired by secondary uses the sensed spectrum holes graphs shows probabilities of detection efficient utilization can be achieved through the graphs by increase the high SNR region will only provide limited gain, experimental held in different scenario with simulator used Mat lab, NS2, and SEAMACAT simulator to justify what actual field measurement values are discussed.

VI. CONCLUSION

To optimize the channel usage patterns monitoring by Pus and Sus is assumed strategy a systematic passive monitoring for finding random sensing and all channel sensing along with TV white space available channel accessing by specifically cooperative sensing ,In this work to detect spectrum hole initially with traditional energy detector and for low SNR scenario cyclostationary detection spectrum sensing was considered Spectrum occupancy involves in secondary with guaranteed interference even in low SNR region. It was also found that the increasing number of SUs can improve detection performance especially in low SNR region.

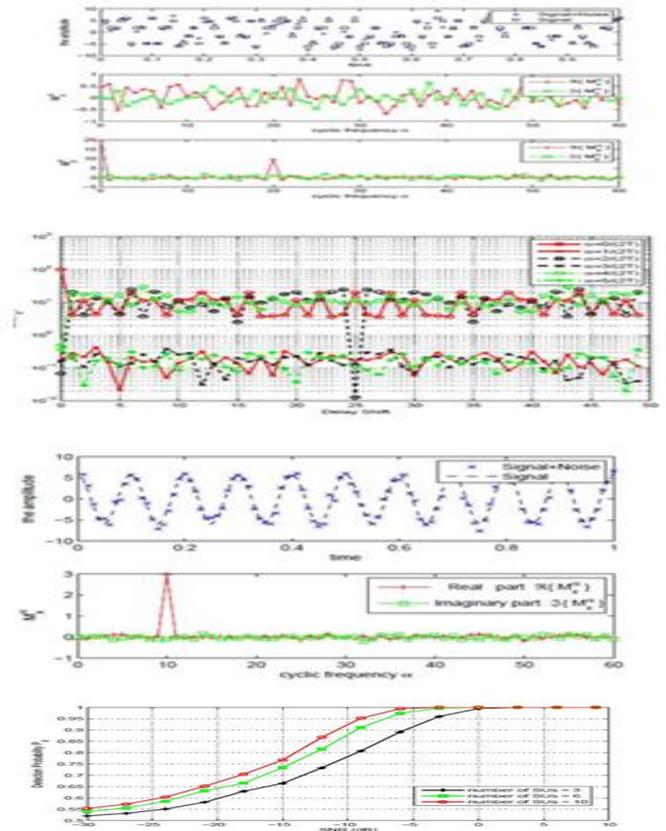


Fig 3: Results graphs snapshots

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